

Query Processing

CPS 216
Advanced Database Systems

Overview

- Many different ways of implementing the same logical query operator
 - Scan, sort, hash, index
 - All with different performance characteristics
- Best choice depends on the situation
 - Implement all alternatives
 - Let the query optimizer choose at run-time

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Notation

- Relations: R, S
- Tuples: r, s
- Number of tuples: $|R|, |S|$
- Number of disk blocks: $B(R), B(S)$
- Number of memory blocks available: M
- Cost metric
 - Number of I/O's
 - Memory requirement

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Table scan

- Scan table R and process the query
 - Selection over R
 - Projection of R without duplicate elimination
- I/O's: $B(R)$
 - Trick for selection:
- Memory requirement: 2 (double buffering)
- Not counting the cost of writing the result out
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Nested-loop join

- $R \triangleright \triangleleft_p S$
- For each block of R , and for each r in the block:
 - For each block of S , and for each s in the block:
 - Output rs if p evaluates to true over r and s
 - R is called the outer table; S is called the inner table
- I/O's: $B(R) + |R| \cdot B(S)$
- Memory requirement: 3 (double buffering)

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Tricks for nested-loop join

- Stop early
 - If the key of the inner table is being matched
 - May reduce half of the I/O's
- Block-based nested-loop join
 - Stuff memory with as much of R as possible, stream S by, and join every S tuple with all R tuples in memory
 - I/O's: $B(R) + \lceil B(R) / (M - 2) \rceil \cdot B(S)$
 - Or, roughly: $B(R) \cdot B(S) / M$
 - Memory requirement: M (as much as possible)

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External merge sort

- Pass 0: read M blocks of R at a time, sort them, and write out a level-0 run
 - There are $\lceil B(R)/M \rceil$ level-0 sorted runs
- Pass i : merge $(M - 1)$ level- $(i-1)$ runs at a time, and write out a level- i run
 - $(M - 1)$ memory blocks for input, 1 to buffer output
 - # of level- i runs = $\lceil \# \text{ of level-}(i-1) \text{ runs} / (M - 1) \rceil$
- Final pass produces 1 sorted run

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Example of external merge sort

- Input: 1, 7, 4, 5, 2, 8, 3, 6, 9
- Pass 0
 - 1, 7, 4 \rightarrow 1, 4, 7
 - 5, 2, 8 \rightarrow 2, 5, 8
 - 9, 6, 3 \rightarrow 3, 6, 9
- Pass 1
 - 1, 4, 7 + 2, 5, 8 \rightarrow 1, 2, 4, 5, 7, 8
 - 3, 6, 9
- Pass 2 (final)
 - 1, 2, 4, 5, 7, 8 + 3, 6, 9 \rightarrow 1, 2, 3, 4, 5, 6, 7, 8, 9

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Performance of external merge sort

- Number of passes: $\lceil \log_{M-1} \lceil B(R)/M \rceil \rceil + 1$
- I/O's
 - Multiply by $2 \cdot B(R)$: each pass reads the entire relation once and writes it once
 - Subtract $B(R)$ for the final pass
 - Roughly, this is $O(B(R) \cdot \log_M B(R))$
- Memory requirement: M (as much as possible)

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Tricks for sorting

- Double buffering
 - Allocate an additional block for each run
 - Trade-off: smaller fan-in (more passes)
- Blocked I/O
 - Instead of reading/writing one disk block at time, read/write a bunch (“cluster”)
 - More sequential I/O’s
 - Trade-off: larger cluster \leftrightarrow smaller fan-in (more passes)
- Replacement sort
 - On average produces level-0 runs that are twice as big
 - Use a priority heap: keep outputting as much as possible and making space for input

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Sort-merge join

- $R \triangleright \triangleleft_{R.A=S.B} S$
- Sort R and S by their join attributes, and then merge
 - r, s = the first tuples in sorted R and S
 - Repeat until one of R and S is exhausted:
 - If $r.A > s.B$ then s = next tuple in S
 - else if $r.A < s.B$ then r = next tuple in R
 - else output all matching tuples, and r, s = next in R and S
- I/O’s: sorting + $B(R) + B(S)$
 - In most cases (e.g., join of key and foreign key)
 - Worst case is $B(R) \cdot B(S)$: everything joins

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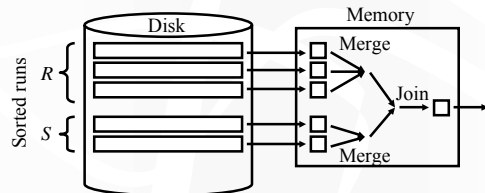
Example

R :	S :	$R \triangleright \triangleleft_{R.A=S.B} S$:
$\Rightarrow r_1.A = 1$	$\Rightarrow s_1.B = 1$	$r_1 s_1$
$\Rightarrow r_2.A = 3$	$\Rightarrow s_2.B = 2$	$r_2 s_3$
$r_3.A = 3$	$\Rightarrow s_3.B = 3$	$r_2 s_4$
$\Rightarrow r_4.A = 5$	$s_4.B = 3$	$r_3 s_3$
$\Rightarrow r_5.A = 7$	$\Rightarrow s_5.B = 8$	$r_3 s_4$
$\Rightarrow r_6.A = 7$		$r_7 s_5$
$\Rightarrow r_7.A = 8$		

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Optimization of SMJ

- Idea: combine join with the merge phase of merge sort
- Sort: produce sorted runs of size M for R and S
- Merge and join: merge the runs of R , merge the runs of S , and merge the result streams as they are generated!



Performance of two-pass SMJ

- I/O's: $3 \cdot (B(R) + B(S))$
- Memory requirement
 - To be able to merge in one pass, we should have enough memory to accommodate one block from each run: $M > B(R) / M + B(S) / M$
 - $M > \text{sqrt}(B(R) + B(S))$

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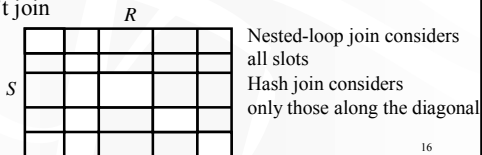
Other sort-based algorithms

- Union, difference, intersection
 - More or less like SMJ
- Duplication elimination
 - External merge sort
 - Eliminate duplicates in sort and merge
- GROUP BY and aggregation
 - External merge sort
 - Produce partial aggregate values in each run
 - Combine partial aggregate values during merge
 - Partial aggregate values don't always work though

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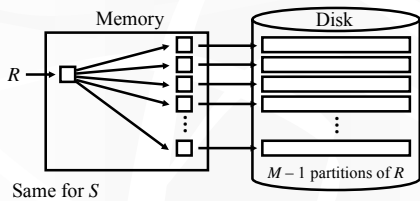
Hash join

- $R \bowtie_{R.A=S.B} S$
- Main idea
 - Partition R and S by hashing their join attributes, and then consider corresponding partitions of R and S
 - If $r.A$ and $s.B$ get hashed to different partitions, they don't join



Partitioning phase

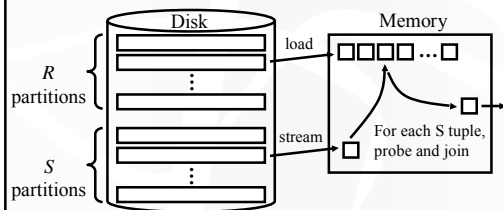
- Partition R and S according to the same hash function on their join attributes



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Probing phase

- Read in each partition of R , stream in the corresponding partition of S , join
 - Typically build a hash table for the partition of R
 - Not the same hash function used for partition, of course!



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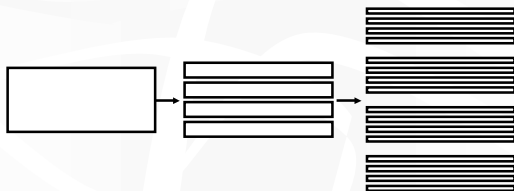
Performance of hash join

- I/O's: $3 \cdot (B(R) + B(S))$
- Memory requirement:
 - In the probing phase, we should have enough memory to fit one partition of R : $M - 1 \geq B(R) / (M - 1)$
 - $M > \sqrt{B(R)}$
 - We can always pick R to be the smaller relation, so: $M > \sqrt{\min(B(R), B(S))}$

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Hash join tricks

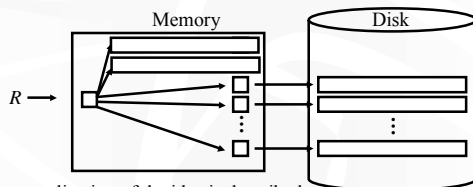
- What if a partition is too large for memory?
 - Read it back in and partition it again!
 - See the duality in multi-pass merge sort here?



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Hybrid hash join

- What if there is extra memory available?
 - Use it to avoid writing/re-reading partitions
 - Of both R and S !



A generalization of the idea is described in the survey paper by Graefe

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Hash join versus SMJ

(Assuming two-pass)

- I/O's: same
- Memory requirement: hash join is lower
 - $\sqrt{\min(B(R), B(S))} < \sqrt{B(R) + B(S)}$
 - Hash join wins when two relations have very different sizes
- Other factors
 - Hash join performance depends on the quality of the hash
 - Might not get evenly sized buckets
 - SMJ can be adapted for inequality join predicates
 - SMJ wins if R and/or S are already sorted
 - SMJ wins if the result needs to be in sorted order

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What about nested-loop join?

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Other hash-based algorithms

- Union, difference, intersection
 - More or less like hash join
- Duplicate elimination
 - Check for duplicates within each partition/bucket
- GROUP BY and aggregation
 - Apply the hash functions to GROUP-BY attributes
 - Tuples in the same group must end up in the same partition/bucket
 - Keep a running aggregate value for each group

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Duality of sort and hash

- Divide-and-conquer paradigm
 - Sorting: physical division, logical combination
 - Hashing: logical division, physical combination
- Handling very large inputs
 - Sorting: multi-level merge
 - Hashing: recursive partitioning
- I/O patterns
 - Sorting: sequential write, random read (merge)
 - Hashing: random write, sequential read (partition)

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