Lecture \# 26
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## 1 Overview

In this lecture, we will examine a technique known as $L P$ rounding. We will first describe the technique at a high level and then give examples of LP rounding algorithms for vertex cover and set cover.

## 2 The Technique

Recall that the goal of approximation is (typically) to design an algorithm for an NP-hard optimization problem that runs in polynomial time ${ }^{1}$. It is futile to try to devise an algorithm that outputs the optimal solution for every instance (or else this would show $\mathrm{P}=\mathrm{NP}$ ), but hopefully we can guarantee that the solutions produced by the algorithm are always within some multiplicative factor of the optimal solution (if this factor is $\alpha$, we say the algorithm is $\alpha$-approximate). As we have seen, the key to proving the approximation factor of an algorithm is lower bounding the cost of the optimal solution (or upper bounding the cost for maximization problems; to keep things simple, we will assume we are dealing with minimization problems for the rest of the notes).

Linear programming provides us with a means of obtaining both a polynomial time algorithm and a lower bound: There are many algorithms that can solve linear programs in weakly-polynomial time. Furthermore, the optimal solution to the fractional relaxation of an integer program is a lower bound on the optimal integral solution (since an integer solution is also a feasible solution to the factional relaxation, the solution can only improve when we remove the requirement of integrality). Therefore, if we can take an optimal solution to an LP relaxation $x^{*}$, specify a method for rounding the fractional values in $x^{*}$ to integer values, and then show that this rounding procedure can only increase the cost of $x^{*}$ by a factor of $\alpha$, then this gives an $\alpha$-approximate polynomial time algorithm (as long as the rounding procedure runs in polynomial time).

The recipe for designing an LP rounding algorithm is shown in Figure 2. Note that ALGO 1 is the always the same: we use some black-box linear programming solver to obtain a fractional solution. The the intricacies (or magic) of every LP rounding algorithm happens in ALGO 2-designing a procedure that rounds the fractional solution to an integer solution.

## 3 Vertex cover: Threshold rounding

Recall the vertex cover problem: given a graph $G=(V, E)$, find a subset of vertices $V^{\prime} \subset V$ of minimum size such that for each $(u, v) \in E, u \in$ or $v \in V$. In Lecture 24 , we gave a greedy algorithm for vertex cover and showed it is a 2 -approximation. We will now see another 2 -approximation algorithm that uses LP rounding.

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Figure 1: Outline for designing an LP rounding algorithm. We start with an integer programming formulation of an NP-hard problem, which we then relax to a linear programming formulation. We then solve this relaxed LP for optimal fractional solution $\mathrm{OPT}_{F}$ (ALGO 1). Next, we feed $\mathrm{OPT}_{F}$ into ALGO 2, which rounds the fractional values in $\mathrm{OPT}_{F}$ to obtain an integer solution $\mathrm{SOLN}_{I}$. To do our analysis, we prove that $\left.\operatorname{Cost}\left(\operatorname{SOLN}_{I}\right)\right) \leq \alpha \cdot \operatorname{Cost}\left(\mathrm{OPT}_{F}\right)$ to show the entire algorithm is an $\alpha$ approximation (since $\mathrm{OPT}_{F}$ is a lower bound on the optimal solution to our NP-hard problem).

Vertex cover can be formulated as the following integer program:

$$
\begin{gather*}
\min \sum_{v \in V} x_{v} \\
\text { s.t. } x_{u}+x_{v} \geq 1 \forall(u, v) \in E  \tag{1}\\
x_{v} \in\{0,1\} \forall v \in V \tag{2}
\end{gather*}
$$

To formulate the LP relaxation, we simply replace our " $x_{v} \in\{0,1\}$ " constraints with $0 \leq x_{v} \leq 1$ (although note that the LP can gains no advantage by setting a variable to be larger than 1 ; therefore, really all we need is the constraint $x_{v} \geq 0$ ). As the first step in our rounding algorithm, we will solve the LP relaxation to obtain an optimal fractional solution $x^{*}$ (which is our $\mathrm{OPT}_{F}$ is the Figure 2).

Next, we round $x^{*}$ in ALGO 2. For our rounding procedure, we will do the simplest thing one can think of: if $x_{v}^{*} \geq 1 / 2$, round $x_{v}^{*}$ up to 1 ; otherwise, round $x_{v}$ down to 0 . Since we are picking a fixed threshold for the rounding boundary that is the same no matter what $x^{*}$ we are given, this technique is called threshold rounding. We then return this rounded solution $\tilde{x}$ as our integer solution (this is $\mathrm{SOLN}_{I}$ in Figure 2).

We first need establish that integer solution is feasible, i.e., every edge is still covered in $\tilde{x}$. This follows directly from that fact that $x^{*}$ is a feasible solution: If there existed an edge $(u, v) \in E$ such that both $\tilde{x}_{v}=0$ and $\tilde{x}_{u}=0$, then, based on the rounding algorithm, we would have $x_{v}^{*}<1 / 2$ and $x_{u}^{*}<1 / 2$. This implies that $x_{v}^{*}+x_{u}^{*}<1$, which is a contradiction since constraint (1) ensures $x *_{v}+x_{u}^{*} \geq 1$.

Finally, we argue that this algorithm is indeed a 2 -approximation by showing $\sum_{v \in V} \tilde{x}_{v} \leq 2 \sum_{v \in V} x_{v}^{*}$. Again, this follows the directly from the rounding procedure. In the worst case, every $x_{v}^{*}=1 / 2$ for all $v \in V$, implying we round all variables up and double their cost. Therefore, the cost of the $\tilde{x}$ can be at most double the cost of $x^{*}$.

## 4 Set cover: Randomized rounding

(Under construction)


[^0]:    ${ }^{1}$ Note that there are approximation algorithms for problems that have polynomial-time exact algorithms. For example, one might try to design a $(1+\varepsilon)$-approximate algorithm that runs in $O(n)$ time for a problem whose best exact solution runs in $O\left(n^{2}\right)$ time

