

Lecture #20

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# 1 Overview

Today, we continue to discuss about metric embeddings technique. Specifically, we apply metric embeddings technique to solve the sparsest cut problem.

## 2 Embedding to $l_p$ norm

$l_p$  norm of a vector  $\mathbf{x}$  is defined by

$$\|\mathbf{x}\|_p = \left(\sum_{i=1}^n x_i^p\right)^{1/p}.$$

In this section, we discuss embedding from any metric space to  $\mathbb{R}^n$  with  $l_p$  norm.

### 2.1 $l_\infty$ norm

Let's first look at  $l_\infty$  norm, where

$$\|\mathbf{x}\|_\infty = \lim_{p \rightarrow \infty} \left(\sum_{i=1}^n x_i^p\right)^{1/p} = \max_i x_i.$$

We say an embedding is *isometric* if the distortion of the embedding is 1.

**Theorem 1.**  $l_\infty$  norm is universal, i.e., given any metric space, there exists an isometric embedding to  $\mathbb{R}^n$  ( $n$  could be arbitrary) with  $l_\infty$  norm.

*Proof.* Assume there are  $n$  points in the original metric space  $\mathcal{M}$ , labelled from 1 to  $k$ . Let  $d(i, j)$  be the distance between the  $i$ -th point and  $j$ -th point in the metric space  $\mathcal{M}$ . Define the embedding function  $f: [n] \rightarrow \mathbb{R}^n$  to be

$$[f(i)]_k = d(i, k)$$

Then, with  $l_\infty$  norm, we have

$$\|f(i) - f(j)\|_\infty = \max_k |f_k(i) - f_k(j)| = \max_k |d(i, k) - d(j, k)| \leq d(i, j)$$

(Triangular inequality is applied in the last inequality.) Moreover, when we choose the index  $k$  to be either  $i$  or  $j$ , (say  $i$ ) we have

$$|f_i(i) - f_i(j)| = |d(i, i) - d(i, j)| = d(i, j)$$

since  $d(i, i) = 0$ . Therefore, we can conclude that

$$\|f(i) - f(j)\|_\infty = d(i, j)$$

□

**Exercise 1.** Show that Euclidean ( $l_2$ ) norm is not universal with the following star graph:  $V = \{1, 2, 3\} \cup \{m\}$  with distance  $d(i, m) = 1$  for all  $i \in \{1, 2, 3\}$  and  $d(i, j) = 2$  for all  $i \neq j$  and  $i, j \in \{1, 2, 3\}$ .

## 2.2 $l_1$ norm

For  $l_1$  norm, we have the following theorem, which we will use without proving for the sparsest cut problem.

**Theorem 2** ([Bou85]). *Any metric space on  $n$  points can be deterministically embedded into an  $l_1$  norm space with  $O(\log^2 n)$  dimension and distortion  $4\log n$ .*

## 3 Sparsest cut

Let  $\partial S$  be the collection of edges in the cut  $(S, V \setminus S)$ :

$$\partial S = \{(i, j) \in E \mid i \in S, j \in V \setminus S\}$$

and denote the capacity of an edge  $(i, j) \in E$  be  $\text{cap}_{ij}$  and the capacity of a cut by

$$\text{cap}(\partial S) = \sum_{(i,j) \in \partial S} \text{cap}_{ij}$$

Consider a graph  $G = (V, E)$ . The sparsity of a cut  $(S, V \setminus S)$  equals

$$\psi(S) = \frac{\text{cap}(\partial S)}{\min(|S|, |V \setminus S|)}$$

In the sparsest cut problem, the objective is to find a cut with minimum sparsity:

$$\phi(G) = \min_{S \subset V} \psi(S)$$

### 3.1 Relate to Flux

The flux of a cut  $G$  is defined by

$$\text{flux}(G) = \min_{S \subset V} \frac{\text{cap}(\partial S)}{|S| \cdot |V \setminus S|}$$

Notice that for each choice of  $S \subset V$ ,

$$\frac{\phi}{\text{flux}} = \frac{|S| \cdot |V \setminus S|}{n \cdot \min(|S|, |V \setminus S|)} = \frac{1}{n} \cdot \max(|S|, |V \setminus S|) \in [1/2, 1]$$

Therefore, if we can get an  $\alpha$  approximation for flux, we can obtain an  $2\alpha$  approximation of  $\phi$ .

### 3.2 Demand

Let's rewrite the flux function,

$$\text{flux}(G) = \min_{S \subset V} \frac{\sum_{(i,j) \in \partial S} \text{cap}_{ij}}{\sum_{(i,j) \in S \times (V \setminus S)} 1}$$

We can view the constant 1 in the above formula as *demand*, which indicates that for each pair  $(i, j) \in S \times V \setminus S$ , we need to push an one-unit flow from  $i$  to  $j$ . The algorithm we are going to present can work if we replace the constant 1 by a demand function:  $\text{dem} : V \times V \rightarrow \mathbb{R}$ . The objective function becomes,

$$f(G) = \min_{S \subset V} \frac{\sum_{(i,j) \in \partial S} \text{cap}_{ij}}{\sum_{(i,j) \in S \times (V \setminus S)} \text{dem}_{ij}}$$

### 3.3 Cut Metric

**Elementary Cut Metric.** An elementary cut metric is a metric defined by a cut  $(S, V \setminus S)$  such that the distance  $d_{ij}$  between  $i$  and  $j$  is 1 if and only if  $i$  and  $j$  are separated by the cut; otherwise,  $d_{ij} = 0$ :

$$d_{ij} = 1 \text{ iff } |\{i, j\} \cap S| = 1$$

With elementary cut metric, we can change the search space from finding a cut to finding an elementary cut metric and rewrite the objective function as follows:

$$f(G) = \min_d \frac{\sum_{(i,j) \in \partial S} \text{cap}_{ij} \cdot d_{ij}}{\sum_{(i,j) \in S \times (V \setminus S)} \text{dem}_{ij} \cdot d_{ij}}$$

**(general) Cut Metric.** A general cut metric is a linear combination of some elementary cut metrics

$$d_{ij} = \sum_{S: |\{i,j\} \cap S|=1} y_S$$

### 3.4 LP formulation

First notice that the value of the objective is the same up to scaling. Therefore, without loss of generality, we can constrain that

$$\sum_{(i,j) \in S \times (V \setminus S)} \text{dem}_{ij} \cdot d_{ij} = 1$$

and turn the objective to be

$$\min \sum_{(i,j) \in \partial S} \text{cap}_{ij} \cdot d_{ij}.$$

The remaining constraints make sure that  $d$  comes from a metric space. The entire program is as follows:

$$\begin{aligned} \min & \sum_{|\{i,j\} \cap S|=1} \text{cap}_{ij} \cdot d_{ij} \\ \text{s.t.} & \sum_{|\{i,j\} \cap S|=1} \text{dem}_{ij} \cdot d_{ij} = 1 \\ & d_{ii} = 0 && \forall i \\ & d_{ij} = d_{ji} && \forall i, j \\ & d_{ij} + d_{jk} \leq d_{ik} && \forall i, j, k \\ & d \text{ is an elementary cut metric} \end{aligned}$$

We change  $\partial S$  to  $S \times (V \setminus S)$  in the above LP by letting  $\text{cap}_{ij} = 0$  if  $(i, j) \in S \times (V \setminus S)$  but  $(i, j) \notin E$  and also rewrite  $(i, j) \in S \times (V \setminus S)$  by  $|\{i, j\} \cap S| = 1$  for simplicity. Finally, in order to obtain an LP, we drop the last constraint so that we compute the best metric instead of the best elementary cut metric.

### 3.5 Analysis

Given the solution metric  $d^*$  from LP, we first apply Theorem 2 to embed it to metric  $d^{l_1}$  in  $\mathbb{R}^{\log^2 n}$  with  $l_1$  norm. In the next step, we turn the  $d^{l_1}$  to a (general) cut metric  $d^{sc}$ , which we will show that this embedding is isometric. Finally, we extract an elementary cut metric  $d^{ec}$  from  $d^{sc}$  to obtain our solution.

**Claim 1.** *Embedding  $d^{l_1}$  to  $d^{sc}$  is isometric.*

*Proof.* Let's first consider the case when  $d^l$  is in one dimension. Therefore, all the points are located on a line. Without loss of generality, assume these points to be  $x_1 < x_2 < \dots < x_n$ . For each  $1 \leq i < n$ , we define a cut between  $x_i$  and  $x_{i+1}$  such that  $S_i = \{1, \dots, i\}$  and let  $y_{S_i} = x_{i+1} - x_i$ . Then, for any pair  $(i, j)$ , we have

$$d_{ij}^l = \sum_{i \leq k < j} y_{S_k} = \sum_{i \leq k < j} x_{k+1} - x_k = x_j - x_i.$$

Therefore, embedding  $d^l$  to  $d^{sc}$  is isometric when  $d^l$  is in one dimension. Notice that  $l_1$  distance between  $\mathbf{x}_i$  and  $\mathbf{x}_j$  is

$$\|\mathbf{x}_i - \mathbf{x}_j\|_1 = \sum_k |(\mathbf{x}_i)_k - (\mathbf{x}_j)_k|$$

Thus, we can apply the argument for one dimension case to each dimension separately to show that the embedding is isometric even when  $d^l$  is in a higher dimension space.  $\square$

Recall that after applying Theorem 2,  $d^l$  is in  $O(\log^2 n)$  dimension. According to the proof of Claim 1, the cut metric  $d^{sc}$  is a linear combination of  $O(n \log^2 n)$  elementary cut metrics (denote the set of these cut by  $EC$ ). Therefore, we can find the elementary cut metric  $d^{ec}$  with minimum objective value in poly time. It remains to show that the elementary cut metric we obtain is a good solution.

$$\begin{aligned} \min_{S \in EC} \frac{\sum_{\{i,j\} \cap S = 1} \text{cap}_{ij}}{\sum_{\{i,j\} \cap S = 1} \text{dem}_{ij}} &= \min_{S \in EC} \frac{y_S \cdot \sum_{\{i,j\} \cap S = 1} \text{cap}_{ij}}{y_S \cdot \sum_{\{i,j\} \cap S = 1} \text{dem}_{ij}} \leq \frac{\sum_{S \in EC} y_S \cdot \sum_{\{i,j\} \cap S = 1} \text{cap}_{ij}}{\sum_{S \in EC} y_S \cdot \sum_{\{i,j\} \cap S = 1} \text{dem}_{ij}} \\ &= \frac{\sum_{(i,j)} \text{cap}_{ij} \cdot \sum_{S \in EC, \{i,j\} \cap S = 1} y_S}{\sum_{(i,j)} \text{dem}_{ij} \cdot \sum_{S \in EC, \{i,j\} \cap S = 1} y_S} = \frac{\sum_{(i,j)} \text{cap}_{ij} \cdot d_{ij}^l}{\sum_{(i,j)} \text{dem}_{ij} \cdot d_{ij}^l} \\ &\leq \frac{\sum_{(i,j)} \text{cap}_{ij} \cdot 4 \log n \cdot d_{ij}^*}{\sum_{(i,j)} \text{dem}_{ij} \cdot d_{ij}^*} \leq 4 \log n LP \leq 4 \log n OPT \end{aligned}$$

The first step is just to multiply  $y_S$  on both the denominator and the nominator, which still keeps the function value the same. The second step applies the following claim

**Claim 2.** If  $a_i > 0$  and  $b_i > 0$  for all  $i$ , we have

$$\min_i \frac{a_i}{b_i} \leq \frac{\sum_i a_i}{\sum_i b_i}.$$

The third step is a change of order of summation while the fourth step uses the fact that  $\sum_{S \in EC, \{i,j\} \cap S = 1} y_S = d_{ij}^{sc}$  and Claim 1. In the fourth step, we apply Theorem 2 with  $d_{ij}^* \leq d_{ij}^l \leq 4 \log n \cdot d_{ij}^*$ .

## 4 Summary

In this lecture, we discuss embedding to  $l_p$  norm and use the embedding to  $l_1$  norm to design an approximation algorithm for the sparsest cut problem [LLR95].

## References

- [Bou85] Jean Bourgain. On lipschitz embedding of finite metric spaces in hilbert space. *Israel Journal of Mathematics*, 52(1):46–52, 1985.
- [LLR95] Nathan Linial, Eran London, and Yuri Rabinovich. The geometry of graphs and some of its algorithmic applications. *Combinatorica*, 15(2):215–245, 1995.