

Lecture 21

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## 1 Overview

Today we continue our discussion on the sparsest cut problem. After a brief review of our LP relaxation method, we start showing why this method has its approximation limit. In the end, we start discussing on a new relaxation method.

## 2 Brief Review

**Definition 1.** For any  $S \subseteq V$ ,  $\partial S := \{(i, j) | i \in S, j \notin S\}$ .

**Definition 2.** Define the *capacity* of an edge set as the sum of the capacities of edges in the set, i.e.  $\text{cap}(E') := \sum_{(i,j) \in E'} c_{ij}$ .

**Definition 3.** Define the *sparsity* of a cut  $(S, V \setminus S)$  as:

$$\psi(S) := \frac{\text{cap}(\partial S)}{\min(|S|, |V \setminus S|)}.$$

Also  $\phi(G) := \min_{S \subseteq V} \psi(S)$ .

**Definition 4.** Define the *flux* of a cut  $(S, V \setminus S)$  as:

$$\text{flux}(S) := \frac{\text{cap}(\partial S)}{|S| \cdot |V \setminus S|}.$$

From the previous lecture we know if we can get an  $\alpha$ -approximation of the minimum-flux cut problem, we get a  $2\alpha$ -approximation of the minimum-sparsity cut problem (and vice versa). We will focus on the minimum-flux cut problem from now on.

**Definition 5.** An *elementary cut metric* given by the cut  $(S, V \setminus S)$  is defined as:

$$l_{ij} := |\{i, j\} \cap S| \bmod 2.$$

**Definition 6.** A *cut metric* is the weighted sum of some elementary cut metrics.

The metric view of the problem is:

$$\min_{\text{cut metric } l} \frac{\sum_{i \in V, j \in V} c_{ij} l_{ij}}{\sum_{i \in V, j \in V} d_{ij} l_{ij}},$$

where the *demand*  $d_{ij} \equiv 1$ . Note that in later discussion, the notion seems to be generalized. In particular, it is possible that  $d_{ij} = 0$  and  $c_{ij} \neq 0$ .

We can write a linear program for the problem:

$$\begin{aligned}
 & \text{minimize} && \sum_{i,j} c_{ij} l_{ij} \\
 & \text{subject to} && \sum_{ij} d_{ij} l_{ij} \geq 1, \\
 & && l_{ij} + l_{jk} \geq l_{ik} \quad \forall i, j, k, \\
 & && l_{ij} \geq 0 \quad \forall i, j.
 \end{aligned}$$

Last time we discussed how this can give a  $O(\log n)$ -approximation by using Bourgain's theorem [Bou85]. Now we are going to show it is the best possible using the LP formulation, by showing its integrality gap.

### 3 Duality View

Consider the maximum concurrent flow problem, which can be formulated by the following LP:

$$\begin{aligned}
 & \text{maximize} && \lambda \\
 & \text{subject to} && \sum_{p \in \mathcal{P}_{ij}} f_p \geq \lambda \cdot d_{ij} \quad \forall i, j, \\
 & && \sum_{p: (i,j) \in p} f_p \leq c_{ij} \quad \forall i, j, \\
 & && f_p \geq 0 \quad \forall p.
 \end{aligned}$$

The dual of it is:

$$\begin{aligned}
 & \text{minimize} && \sum_{i,j} c_{ij} \beta_{ij} \\
 & \text{subject to} && \sum_{i,j} \alpha_{ij} d_{ij} \geq 1, \\
 & && \left( \sum_{(i,j) \in p} \beta_{ij} \right) - \alpha_{p,p_t} \geq 0 \quad \forall p, \\
 & && \alpha_{ij}, \beta_{ij} \geq 0 \quad \forall i, j.
 \end{aligned}$$

In fact, this dual is equivalent to the LP formulation of the sparsest cut problem. To see that, notice  $\alpha_{ij}$  is at most the shortest path distance under  $\beta_{ij}$ 's, and has no reason to be smaller.

### 4 Integrality Gap for the Linear Programming Formulation

**Example 1.** Consider the graph in Figure 1. Every bold black edge has  $c = 1$  and  $d = 0$ . Every red dotted edge has  $c = 0$  and  $d = 1$ . Then the minimum sparsity is 1 (by cutting only the upper right vertex). However, our LP has a solution of  $\frac{3}{4}$ , by setting the metric as follows: Every two vertices on the same-hand side (i.e. connected by a red dotted edge) has a distance of 2. Every other pair of vertices has a distance of 1. Therefore we know our LP formulation has an integrality gap of  $\frac{4}{3}$ .

In fact, we can have better bounds by looking at *expander graphs*.

**Definition 7.** A *constant-degree expander* is a graph in which

$$\min_{S \in V, |S| \leq \frac{|V|}{2}} \frac{|\partial S|}{|S|} = \Omega(1).$$

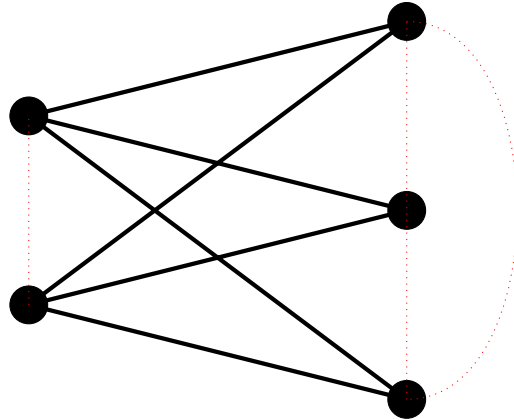


Figure 1: An Example to Show the Integrality Gap

Consider the graph where we assign each vertex to have three random neighbors. It is a constant-degree expander and there are  $\Omega(n^2)$  pairs of vertices at a distance of  $\Omega(\log n)$  from each other. In such a graph, the actual optimum is only  $\Theta\left(\frac{1}{n}\right)$ , but our relaxation will result in a solution of  $\Theta\left(\frac{1}{n \log n}\right)$ . This shows an integrality gap of  $\Theta(\log n)$ .

## 5 New Idea

To avoid the  $\Theta(\log n)$  integrality gap, we will try the following idea: instead of relaxing  $l_1$ -norm to any metric, we relax  $l_1$ -norm to  $l_2^2$ -metrics. Notice that in order that  $l_2^2$  is a metric, all angles between the points must be *acute* (by the law of cosines). We will elaborate on this idea in the next lecture.

## 6 Summary

Today we discussed further on the sparsest cut problem. We provided a duality view of our LP relaxation, showed its integrality gap, and started talking about another way to relax the problem. We will continue on this topic in the next lecture.

## References

[Bou85] Jean Bourgain. On lipschitz embedding of finite metric spaces in hilbert space. *Israel Journal of Mathematics*, 52(1):46–52, 1985.