## XML Query Processing

CPS 216 Advanced Database Systems

#### Announcements (March 23)

- ❖ Course project milestone 2 due in a week (March 30)
- ❖ Homework #3 due in two weeks (April 6)
- \* Talk by Rachel Pottinger
  - Processing Queries and Merging Schemas in Support of Data Integration
  - Thursday, 11:30am-12:30pm, D106
- \* Recitation session this Friday
  - XML API's
- \* No classes next week
  - Make up during reading period

#### Overview

- ❖ Recall that XML queries based on path expressions can be expressed by joins
- ❖ Node/edge-based representation (graphs)
  - Equi-join on id's
  - Chasing pointers ≈ index nested-loop joins
     "Navigational" approach
- Interval-based representation (trees)
  - "Containment" joins involving left and right
  - Sort-merge joins, zig-zag joins with indexes
     "Structural" approach

#### Navigational processing in Lore

#### VLDB 1999

- Lore data model peculiarity: labels on edges instead of labels on nodes
- \* Access paths in Lore
  - Base representation: (parent, label) → child
  - Label index: (child, label) → parent
  - Edge index: label  $\rightarrow$  (parent, child)
  - Value index: (value, label) → node
  - lacksquare Path index: path expression ightarrow node
- Correspond to the following in a label-on-node model
  - label/value  $\rightarrow$  node
  - (parent, label)  $\rightarrow$  child
  - child → parent

# Navigational plans in Lore

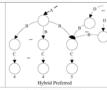
//A/B/C[.=5]

- \* Top down: pointer chasing
  - $\blacksquare$  Start with //A, navigate down to //A/B and then to //A/B/C, and then check values of C
- \* Bottom up: reverse pointer chasing
  - Start with //C[.=5], navigate up to //B[/C[.=5]] and then to //A[/B/C[.=5]]
- \* Hybrid: top down and bottom up, meet in middle
  - Start with //A, navigate down to //A/B
  - Start with //C[.=5], navigate up to //B[/C[.=5]]
  - Intersect B nodes
  - In general, hybrid can combine multiple top-down and bottom-up plans starting from anywhere in the path expression

# Comparison of Lore navigational plans







- Which plan is best depends on the size of the intermediate results it generates
  - Choose the optimal join order!
- Top down and bottom up are essentially index nested-loop joins ("pure" navigation)
- \* Hybrid can use any join strategy to combine subplans

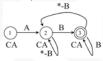
#### Niagara unnest

VLDB 2003

- ❖ Unnest: navigation-style processing using finite state machines A → B → B
- \* Example: A/B CA CA
  - Given a list of elements for which A/B needs to be evaluated
  - Each state maintains a cursor
  - For each given element, state 1 uses a CA (child-axis) cursor with label A to iterate through all A children
  - For each A child, state 2 uses a CA cursor with label B to iterate through all B children of the A child
- \* Essentially a sequence of indexed nested-loop joins
  - Top down or bottom up, but not hybrid

# Alternative unnest strategies for //

- ❖ Example: A//B
- ❖ Using CA cursors only



- Using DA (descendent-axis) cursor
  - Given node *n* and label A, a DA cursor iterates through all *n*//A nodes in document order



## Surprise with the DA cursor

- Recall that XPath expressions are supposed to return result nodes in document order
- ❖ Example: /A//B/C
  - DA enumerates descendents in document order
  - But subsequent steps may produce out-of-order results

A problem for CA as well?



#### Structural approach

- ❖ Binary containment joins (Al-Khalifa et al., ICDE 2002)
  - Given Alist and Dlist, two lists of elements encoded with (left, right), with each list sorted by left
  - Find all pairs of (a, e), where a ∈ Alist and e ∈ Dlist, such that a is a parent (or ancestor) of e
- Example query processing scenario: //book/author
  - Using an inverted-list index, retrieve the list of book elements sorted by left, and the list of author elements sorted by left
  - Find pairs that actually form parent-child relationships

# Tree-based algorithms

Algorithm Tree-Merge-Anc

Begin Joinable = 0;

For each a in Alist:

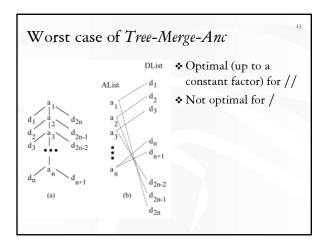
Start from BeginJoinable and skip Dlist until the first element with left > a.left; update BeginJoinable; Start from BeginJoinable and join each d from Dlist with a; stop at the first d with left > a.right;

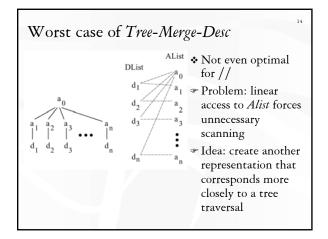
 An alternative algorithm, Tree-Merge-Desc, uses Dlist as the outer table instead of Alist, and requires minor tweaks to conditions

# Tree-Merge-Anc example

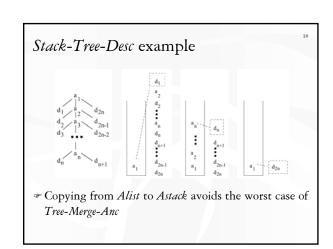
- $a_1$ : BeginJoinable =  $d_1$ ; stops at  $d_4$
- $A_2$ : BeginJoinable =  $d_2$ ; stops at  $d_4$
- $A_3$ : BeginJoinable =  $d_4$ ; stops at  $d_6$
- $a_4$ : BeginJoinable =  $d_6$
- Further optimization is possible to avoid unnecessary rescanning; though in general rescanning cannot be avoided

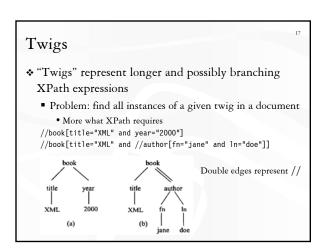
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# Stack-based algorithms Algorithm Stack-Tree-Desc Start with an empty stack Astack While Astack or Alist or Dlist is not empty: If heads of both Alist and Dlist come after the top of Astack, pop Astack; Else if the head of Alist is contained by the top of Astack, push it onto Astack and advance Alist; Else join the head of Dlist with everything on Astack and advance Dlist; Output is ordered by Dlist An alternative algorithm, Stack-Tree-Anc, orders output by Alist but requires more bookkeeping





Holistic twig join

\* Traditional approach: use a sequence of binary containment joins to process a twig

\* Problem: intermediate results can get much larger than input and output sizes

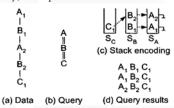
• Example?

\* Idea: use a multi-way merge (since all joins are on the same attributes)

• "Holistic" twig join (Bruno et al., SIGMOD 2002)

## Compact encoding using stacks

- \* One stack for each node in the query twig
  - Elements in a stack form a containment chain
- \* Each stack element points to one in the parent stack
  - Specifically, the top one that contains it



#### PathStack

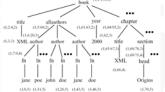
- ❖ Handles twigs with no branches q1//q2//...//qn
- . Input lists  $T_{q1},\,T_{q2},\,...,\,T_{qn}$  and stacks  $S_{q1},\,S_{q2},\,...,\,S_{qn}$
- ❖ While T<sub>an</sub> is not empty:

Let  $T_{q_{min}}^q$  be the list whose head has smallest left; Clean all stacks: pop while top's  $right < head(T_{q_{min}}).left$ ; Push  $head(T_{q_{min}})$  on  $S_{q_{min}}$ , with pointer to  $top(S_{parent}(q_{min}))$ ; If  $q_{min}$  is the leaf (qn), output results and pop  $S_{q_{min}}$ ;

- Check properties
  - · Elements in a stack form a containment chain
  - Each stack element points to the top one in the parent stack that contains it

## Extending PathStack to TwigStack

- ❖ A first cut
  - Decompose a twig into root-to-leaf paths
  - Process each path using PathStack
  - Merge solutions for all paths
- \* Problem: intermediate results may be big



All authors will be returned by *PathStack*, though only the last one should be

in the final result

# TwigStack

- ❖ Generate solutions for each root-to-leaf path
  - Do not use *PathStack*, which generates all solutions
  - Modify *PathStack* to generate only solutions that are parts of the final result (possible if twig contains only //)
     Specifically, when pushing h<sub>q</sub> onto stack S<sub>q</sub>, ensure that
    - •  $b_q$  has a descendent  $b_{q'}$  in the each input list  $T_{q'}$  where q' is a child of q
    - ullet Each  $b_{q'}$  recursively satisfies the above property
- Merge solutions for all paths

# TwigStack still suboptimal for /

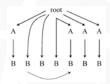
\* Example



- Desired result:  $(A_1, B_2, C_2), (A_2, B_1, C_1)$
- Initial state: all three stacks empty; ready to push one of A<sub>1</sub>,
   B<sub>1</sub>, C<sub>1</sub> onto a stack
- If we want to ensure that non-contributing nodes are never pushed onto the stack, then
  - Cannot decide on  $A_1$  unless we see  $B_2$  and  $C_2$
  - Cannot decide on  $B_1$  or  $C_1$  unless we see  $A_2$

# Optimization using an index

- Idea: if there are indexes on input lists ordered by left, use these indexes to skip lists more efficiently
- ❖ Example: Niagara's ZigZag join on A//B



- After advancing to the second A, use the index on B list to go directly to the first joining B, instead of scanning B list linearly
- When processing a B, use the index on A list to skip

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Summary of structural approach

- What makes XML containment joins easier than joining lists of arbitrary intervals?
  - Intervals form either disjoint or containment relationships, but they cannot overlap
  - This property is heavily exploited by stack-based algorithms
- Most algorithms in literature assume that bindings must be produced for all nodes in a twig
  - Unnecessary requirement in practice
  - Leads to potentially much larger result sizes
  - Is it possible to have more efficient algorithms that produce bindings for only selected nodes in a twig?

Navigational vs. structural approaches

- In the past some has argued that structural is preferable to navigational
- Niagara argues for a mixed-mode approach, using a cost-based analysis to pick which approach or combination of approaches is better
  - Just like one would implement both index nested-loop join and sort-merge join

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