Touay S	topics			ion Values om variable <i>V</i> having a nume	eric domain its		
<ul><li>Reading</li><li>Upcomi</li></ul>	eted value g: Sections 5.3		• The term "expectation v value or (arity probability di $\hat{V} := \mathbf{Ex}[$ • The term "ex - But this term value might • E.g., if $p(0)$ we know t	<u>value</u> or <u>expected value</u> or <u>we</u> <u>hmetic) mean value</u> $\mathbf{Ex}[V]$ , u istribution $\Pr[v] = p(v)$ , is de $[V] := \mathbf{Ex}_p[V] := \sum_{v \in \mathbf{dom}[V]} 1$ pected value" is very widely n is somewhat misleading, since to itself be totally unexpected, or ev $[V] = 0.5 \& p(2) = 0.5$ , then $\operatorname{Ex}[V] = 1$ , even to	$\frac{p_{ighted average}}{p_{inder the}}$ fined as $p \cdot p(v)$ . used for this. he "expected" ven impossible! hough $p(1)=0$ and so		
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Derived	Random Variables		Linearity	of Expectation Value	S		
<ul> <li>variable</li> <li>Then, an consider value <i>f(V</i>)</li> <li>If the ran</li> </ul>	a sample space over values of V (representing possible outco y function f over S can also be ed to be a random variable (wi ) is derived from the actual va- nge $R = range[f]$ of f is numeri- lue $\mathbf{Ex}[f]$ of f can still be defin	omes). e hose actual alue of <i>V</i> ). ic, then the	derived f subject to • Then we $Ex[X_1+X]$ $Ex[aX_1 + V]$ • You show	<ul> <li>Let X<sub>1</sub>, X<sub>2</sub> be any two random variables derived from the <i>same</i> sample space S, and subject to the same underlying distribution.</li> <li>Then we have the following theorems: Ex[X<sub>1</sub>+X<sub>2</sub>] = Ex[X<sub>1</sub>] + Ex[X<sub>2</sub>] Ex[aX<sub>1</sub> + b] = aEx[X<sub>1</sub>] + b</li> <li>You should be able to easily prove these for yourself at home.</li> </ul>			
	$\hat{f} = \mathbf{E}\mathbf{x}[f] = \sum_{s \in S} p(s) \cdot f(s)$			sen at nonne.			

## Variance & Standard Deviation

The variance Var[X] = σ<sup>2</sup>(X) of a random variable X is the expected value of the square of the difference between the value of X and its expectation value Ex[X]:

 $\mathbf{Var}[X] := \sum_{s \in S} \left( X(s) - \mathbf{Ex}_p[X] \right) p(s)$ 

• The standard deviation or root-mean-square (RMS) difference of X is  $\sigma(X) := \operatorname{Var}[X]^{1/2}$ .

## Entropy

- The *entropy H* of a probability distribution *p* over a sample space *S* over outcomes is a measure of our *degree of uncertainty* about the actual outcome.
  - It measures the expected amount of increase in our known information that would result from learning the outcome.

$$H(p) := \mathbf{E}\mathbf{x}_p[\log p^{-1}] = -\sum_{s \in S} p(s)\log p(s)$$

- The base of the logarithm gives the corresponding unit of entropy; base  $2 \rightarrow 1$  bit, base  $e \rightarrow 1$  nat (as before)
  - 1 nat is also known as "Boltzmann's constant"  $k_{\rm B}$  & as the "ideal gas constant" R, and was first discovered physically

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## **Visualizing Entropy**

