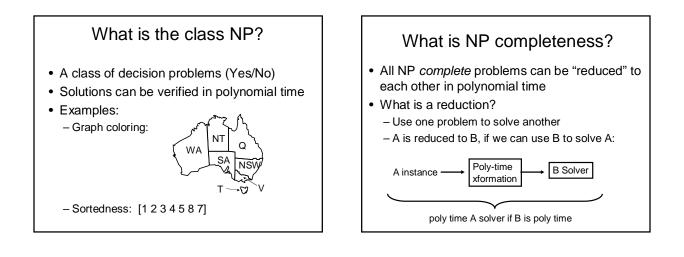
# NP Hardness & CSPs CPS 170

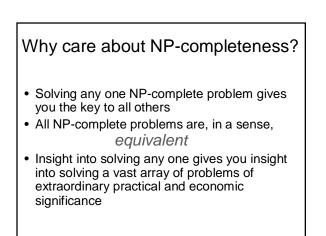
Ron Parr

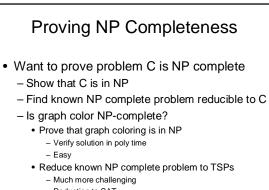
## NP-hardness

- Many problems in AI are NP-hard (or worse)
  What does this mean?
  These are some of the hardest problems in CS
  Identifying a problem as NP hard means:

  You probably shouldn't waste time trying to find a polynomial time solution
  If you find a polynomial time solution, either
  You have a bug
  Find a place on your shelf for your Turing award
- NP hardness is a major triumph (and failure) for computer science theory







- Reduction to SAT

# The First NP Complete Problem (Cook 1971)

• SAT:

$$(X_1 \vee \overline{X}_7 \vee X_{13}) \wedge (\overline{X}_2 \vee X_{12} \vee X_{25}) \wedge \dots$$

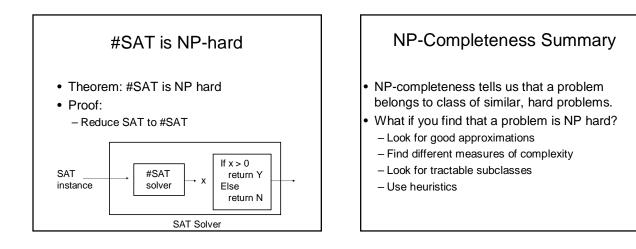
- Want to find an assignment to all variables that makes this expression evaluate to true
- NP-complete for clauses of size 3 or greater
- · How would you prove this?

### What is NP Hardness?

- NP hardness is weaker than NP completeness
- NP hard if an NP complete problem is reducible to it
- NP completeness = NP hardness + NP membership
- Consider the problem #SAT
   How many satisfying assignments to:

$$(X_1 \vee \overline{X}_7 \vee X_{13}) \wedge (\overline{X}_2 \vee X_{12} \vee X_{25}) \wedge \dots$$

- Is it NP-hard?



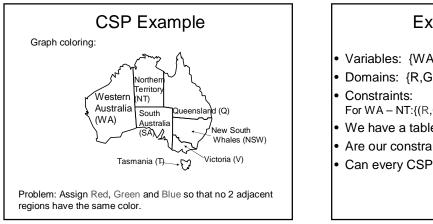
### **CSPs**

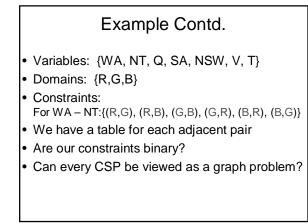
- What is a CSP?
- · One view: Search with special goal criteria
- CSP definition (general):
  - Variables X<sub>1</sub>,...,X<sub>n</sub>
  - Variable X<sub>i</sub> has domain D<sub>i</sub>
  - Constaints C1,...,Cm
  - Solution: Each variable gets a value from its domain such that no constraints violated
- CSP examples...
  - http://4c.ucc.ie/~tw/csplib/

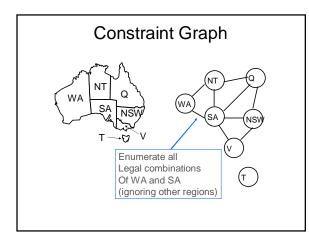
# Our Restricted View

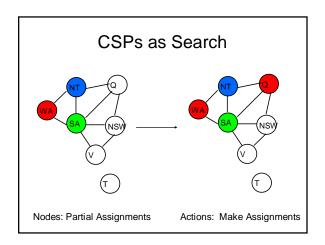
- Variables X<sub>1</sub>,...,X<sub>n</sub>
- A binary constraint, lists permitted assignments to pairs of variables
- A binary constraint between binary variables is a table of size 4, listing legal assignments for all 4 combinations.
- A k-ary constraint lists legal assignments to k variables at a time.
- How large is a k-ary constraint for binary variables?

Note: More expressive languages are often used.









# Backtracking

- Backtracking is the most obvious (and widely used) method for solving CSPs:
  - Search forward by assigning values to variables
  - If stuck, undo the most recent assignment and try again
  - Repeat until satisfying assignment found or all
  - combinations tried
- Embellishments
  - Methods for picking next variable to assign
    - Most constrained
      Least constrained
    - Least constraine
  - Backjumping

# NP-Completeness of CSPs

- Are CSPs in NP?
- Are they NP-hard?
- CSPs and graph coloring are equivalent
  - · Convert any graph coloring problem to CSP
  - Convert any CSP to graph coloring
- Graph coloring is NP-complete
- CSPs are NP-complete
- End of the story or just the beginning?

#### Issues

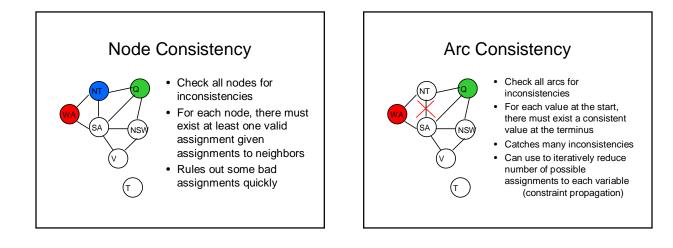
- · What are good heuristics?
  - Often good to think of this as a local search
  - Focus on choosing actions carefully, instead of pruning nodes carefully
- Can we develop heuristics that apply to the entire class of problems, not just specific instances?
- What's the best we can hope for?

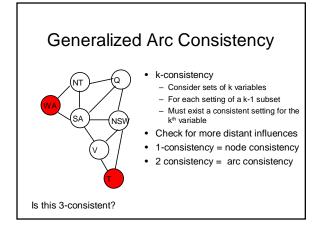
## **Constraint Graphs**

Constraint graphs are important because they capture the structural relationships between the variables

#### IMPORTANT CONCEPT:

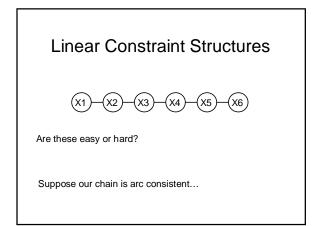
- Not all instances of a hard problem class are hard
- Structural features give insight into hardness
- Group problems within class by structural features
- New measure of problem complexity





# Facts About Arc Consistency

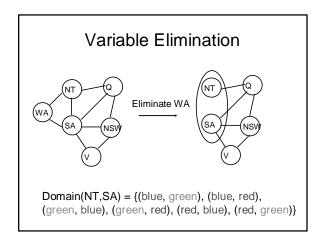
- What if a graph with n variables is nconsistent?
- What is the worst-case cost of checking n-consistency?

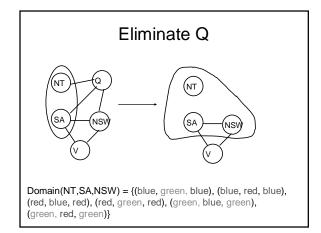


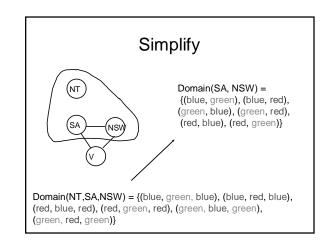
Properties of Chains

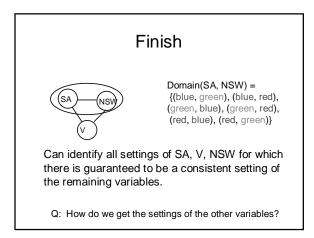
Theorem: Arc consistent linear constraint graphs are n consistent.

Properties of Trees Theorem: Arc consistent constraint trees are n consistent.





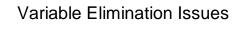




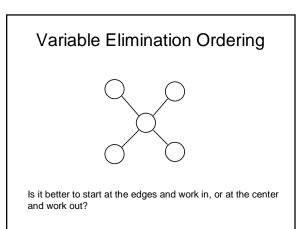
# Variable Elimination

 $Var\_elim\_CSP\_solve (vars, constraints)$  Q = queue of all variables i = length(vars)+1While not(empty(Q)) X = pop(Q) Xi = merge(X, neighbors(X))Simplify Xi remove\_from\_Q(Q, neighbors(X)) add\_to\_Q(Q, Xi) i=i+1

Note: Merge operation can be tricky to implement, depending upon constraint language.



- · How expensive is this?
- Is it sensitive to elimination ordering?

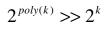


### Variable Elimination Facts

- You can figure out the cost of a particular elimination ordering without actually constructing the tables
- Finding optimal elimination ordering is NP hard
- Good heuristics for finding near optimal orderings
- Another structural complexity measure
- Investment in finding good ordering can be amortized



- Structural complexity is a somewhat different view of computational complexity: depends upon problem features, not problem class
- For many problems structural complexity is quite manageable
- Idea: Why not convert other NP-hard problems to CSPs and use structural complexity measures, CSP algorithms to solve?



# CSP Summary

- CSPs are a specialized language for describing certain types of decision problems
- We can formulate special heuristics and methods for problems that can be described in this language
- In general, CSPs are NP hard
- We can use structural measures of complexity to figure out which ones are really hard