296.3: Algorithms in the Real World

Error Correcting Codes III (expander based codes)

- Expander graphs
- Low density parity check (LDPC) codes
- Tornado codes

Thanks to Shuchi Chawla for many of the slides

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Why Expander Based Codes?

Linear codes like RS & random linear codes

The other two give nearly optimal rates But they are slow:

<u>Code</u>	<u>Encoding</u>	<u>Decoding</u>
Random Linear	O(n ²)	O(n ³)
RS	O(n log n)	O(n ²)
LDPC	O(n²) or better	O(n)
Tornado	O(n log 1/ε)	O(n log 1/ε)

Assuming an $(n, (1-p)n, (1-\epsilon)pn+1)_2$ tornado code

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Error Correcting Codes Outline

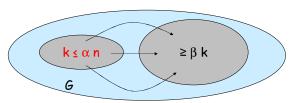
Introduction Linear codes Read Solomon Codes Expander Based Codes



- Expander Graphs
- Low Density Parity Check (LDPC) codes
- Tornado Codes

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Expander Graphs (non-bipartite)

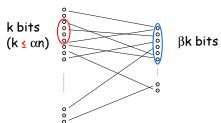


<u>Properties</u>

- Expansion: every small subset (k ≤ αn) has many
 (≥ βk) neighbors
- Low degree not technically part of the definition, but typically assumed

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Expander Graphs (bipartite)



<u>Properties</u>

- Expansion: every small subset ($k \le \alpha n$) on left has many ($\ge \beta k$) neighbors on right
- Low degree not technically part of the definition, but typically assumed

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Expander Graphs

Useful properties:

- Every set of vertices has many neighbors
- Every balanced cut has many edges crossing it
- A random walk will quickly converge to the stationary distribution (rapid mixing)
- The graph has "high dimension"
- Expansion is related to the eigenvalues of the adjacency matrix

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Expander Graphs: Applications

Pseudo-randomness: implement randomized algorithms with few random bits

Cryptography: strong one-way functions from weak ones.

Hashing: efficient n-wise independent hash functions

Random walks: quickly spreading probability as you walk through a graph

Error Correcting Codes: several constructions
Communication networks: fault tolerance, gossip-based protocols, peer-to-peer networks

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d-regular graphs

An undirected graph is <u>d-regular</u> if every vertex has d neighbors.

A bipartite graph is <u>d-regular</u> if every vertex on the left has d neighbors on the right.

The constructions we will be looking at are all dregular.

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Expander Graphs: Eigenvalues

Consider the normalized adjacency matrix A_{ij} for an undirected graph G (all rows sum to 1)

The (x_i, λ_i) satisfying

$$A \times_{i} = \lambda_{i} \times_{i}$$

are the eigenvectors and eigenvalues of A.

Consider the eigenvalues $\lambda_0 \ge \lambda_1 \ge \lambda_2 \ge ...$

For a d-regular graph, $\lambda_0 = 1$. Why?

The separation of the eigenvalues tell you a lot about the graph (we will revisit this several times).

If λ_1 is much smaller than λ_0 then the graph is an expander.

Expansion $\beta \ge (1/\lambda_1)^2$

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Expander Graphs: Constructions

Important parameters: size (n), degree (d), expansion (β)

Randomized constructions

- A random d-regular graph is an expander with a high probability
- Construct by choosing d random perfect matchings
- Time consuming and cannot be stored compactly

Explicit constructions

- Cayley graphs, Ramanujan graphs etc
- Typical technique start with a small expander, apply operations to increase its size

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Expander Graphs: Constructions

Start with a small expander, and apply operations to make it bigger while preserving expansion

Squaring

- G² contains edge (u,w) if G contains edges (u,v) and (v,w) for some node v
- $A' = A^2 1/d I$
- $\lambda' = \lambda^2 1/d$
- $d' = d^2 d$

Size ≡ Degree ↑ Expansion ↑

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Expander Graphs: Constructions

Start with a small expander, and apply operations to make it bigger while preserving expansion

Tensor Product (Kronecker product)

- $G = A \times B$ nodes are $(a,b) \forall a \in A \text{ and } b \in B$
- edge between (a,b) and (a',b') if A contains (a,a') and B contains (b,b')
- $n' = n_A n_B$
- $\lambda' = \max(\lambda_A, \lambda_B)$
- $d' = d_A d_B$

Size ↑
Degree ↑
Expansion ↓

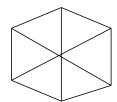
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Expander Graphs: Constructions

Start with a small expander, and apply operations to make it bigger while preserving expansion

Zig-Zag product

- "Multiply" a big graph with a small graph





$$n_2 = d_1$$

 $d_2 = (d_1)^{1/4}$

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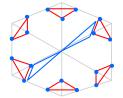
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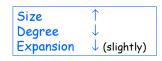
Expander Graphs: Constructions

Start with a small expander, and apply operations to make it bigger while preserving expansion

Zig-Zag product

- "Multiply" a big expander with a small expander





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Combination: square and zig-zag

For a graph with size n, degree d, and eigenvalue λ , define G = (n, d, λ). We would like to increase n while holding d and λ the same.

Squaring and zig-zag have the following effects:

$$(n, d, \lambda)^2 = (n, d^2, \lambda^2) \equiv \uparrow \uparrow$$

$$(n_1, d_1, \lambda_1) zz (d_1, d_2, \lambda_2) = (n_1d_1, d_2^2, \lambda_1 + \lambda_2 + \lambda_2^2) \uparrow \downarrow \downarrow$$

Now given a graph H = $(d^4, d, 1/5)$ and $G_1 = (d^4, d^2, 2/5)$

-
$$G_i = (G_{i-1}^2)$$
 zz H (square, zig-zag)

Giving: $G_i = (n_i, d^2, 2/5)$ where $n_i = d^{4i}$ (as desired)

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Error Correcting Codes Outline

Introduction

Linear codes

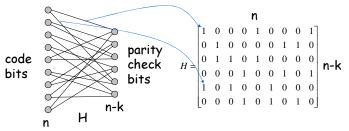
Read Solomon Codes

Expander Based Codes

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Low Density Parity Check (LDPC) Codes



Each row is a vertex on the right and each column is a vertex on the left.

A codeword on the left is valid if each right "parity check" vertex has parity 0.

The graph has O(n) edges (low density)

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Applications in the "real world"

10Gbase-T (IEEE 802.3an, 2006)

- Standard for 10 Gbits/sec over copper wire WiMax (IEEE 802.16e, 2006)

Standard for medium-distance wireless.
 Approx 10Mbits/sec over 10 Kilometers.

NASA

- Proposed for all their space data systems

<u>History</u>

Invented by Gallager in 1963 (his PhD thesis)

Generalized by Tanner in 1981 (instead of using parity and binary codes, use other codes for "check" nodes).

Mostly forgotten by community at large until the mid 90s when revisited by Spielman, MacKay and others.

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Distance of LDPC codes

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Consider a d-regular LPDC with $(\alpha, 3d/4)$ expansion.

 $\underline{\textbf{Theorem}}\text{: Distance of code is greater than }\underline{\alpha}n.$

<u>Proof</u>. (by contradiction)

Suppose we change a code word in v bits, $v \le \alpha n$.

Let V be the set of changed bits in codeword V has > (3/4)dv neighbors on the right Average # of changed bits per such neighbor is < 4/3.

To make average work, at least one neighbor has only 1 changed bit... which would cause a non-zero syndrome.

d = degree

V

neighbors

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Correcting Errors in LPDC codes

We say a check bit is <u>unsatisfied</u> if parity $\neq 0$

Algorithm:

While there are unsatisfied check bits

- Find a bit on the left for which more than d/2 neighbors are unsatisfied
- 2. Flip that bit

Converges since every step reduces unsatisfied nodes by at least 1.

Runs in linear time.

Why must there be a node with more than d/2 unsatisfied neighbors?

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A node with d/2 unsatisfied neighbors

Let $r \le \alpha n$ be number of error bits.

If none of the error bits has more than d/2 unshared check-bit neighbors error bit (i.e., not shared with any other error bit), then total number of neighbors is at most (d/2)r+((d/2)r)/2 = 3dr/4.

But the error bits have more than (3/4)dr neighbors, a contradiction.

Finally, every unshared neighbor must be unsatisfied.

unshared neighbor

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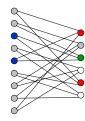
Coverges to closest codeword

Theorem: If # of error bits is less than an/4 with 3d/4 expansion then the simple decoding algorithm will converge to the closest codeword.

Proof: let:

- u_i = # of unsatisfied check bits on step i
- r; = # corrupt code bits on step i
- s_i = # satisfied check bits with corrupt neighbors on step i

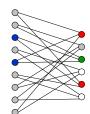
We know that u_i decrements on each step, but what about r_i ?



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Proof continued:



- u_i = unsatisfied
- r_i = corrupt
- s_i = satisfied with corrupt neighbors

$$u_i + s_i > \frac{3}{4} dr_i$$
 (by expansion)

$$2s_i + u_i \le dr_i$$
 (by counting edges)

$$\frac{1}{2}dr_i \le u_i \quad \text{(by substitution)}$$

 $u_i < u_0$ (steps decrease u) $u_0 \le dr_0$ (by counting edges)

Therefore: $r_i < 2r_0$ i.e., number of corrupt bits cannot more than double

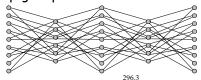
If we start with at most $\alpha n/4$ corrupt bits we will never get $\alpha n/2$ corrupt bits but the distance is > αn

More on decoding LDPC

Simple algorithm is only guaranteed to fix half as many errors as could be fixed but in practice can do better

Fixing (d-1)/2 errors is NP hard

Soft "decoding" as originally specified by Gallager is based on belief propagation---determine probability of each code bit being 1 and 0 and propagate probs. back and forth to check bits.



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Encoding LPDC

Encoding can be done by generating G from H and using matrix multiply.

What is the problem with this? (G might be dense) Various more efficient methods have been studied

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Error Correcting Codes Outline

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- Tornado Codes

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The loss model

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Random Erasure Model:

- Each bit is lost independently with some probability $\boldsymbol{\mu}$
- We know the positions of the lost bits

For a <u>rate</u> of (1-p) can correct (1- ϵ)p fraction of errors.

Seems to imply a

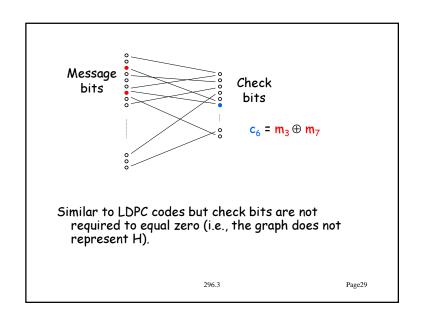
 $(n, (1-p)n, (1-\epsilon)pn+1)_2$

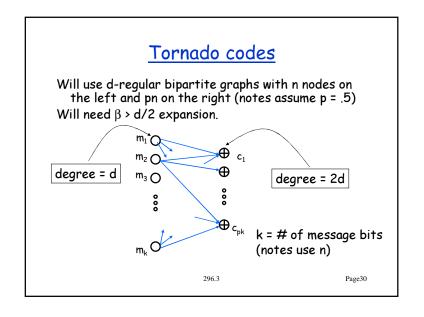
code, but not quite because of random errors assumption.

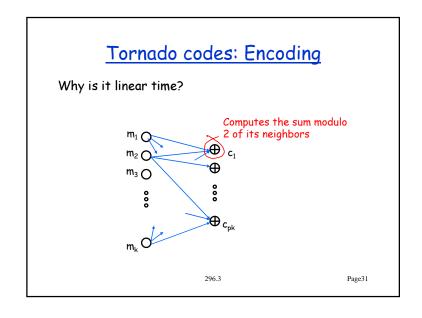
We will assume p = .5.

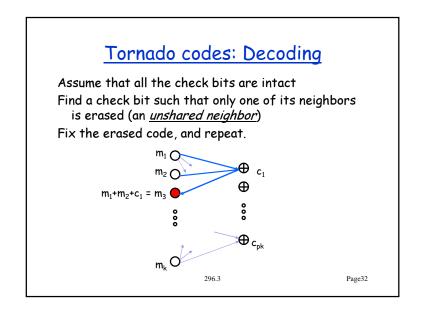
Error Correction can be done with some more effort

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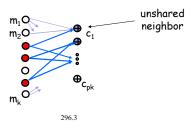


Tornado codes: Decoding

Need to ensure that we can always find such a check bit "Unshared neighbors" property

Consider the set of corrupted message bits and their neighbors. Suppose this set is small.

=> at least one corrupted message bit has an unshared neighbor.



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Tornado codes: Decoding

Can we always find unshared neighbors?

Expander graphs give us this property if $\beta > d/2$ (similar to argument previous argument that $\beta > 3d/4$ implies d/2 unshared neighbors)

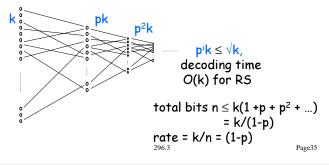
Also, [Luby et al] show that if we construct the graph from a specific kind of non-regular degree sequence (derived from differential equations!), then we can always find unshared neighbors.

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What if check bits are lost?

Cascading

- Use another bipartite graph to construct another level of check bits for the check bits
- Final level is encoded using RS or some other code



Cascading

Encoding time

- for the first i stages : $|E| = d \times |V| = O(k)$
- for encoding the last stage w/RS: $O((\sqrt{k}) \log \sqrt{k}) = O(k)$

Decoding time

- start from the last stage and move left
- again proportional to |E|
- also proportional to d, which must be at least $1/\epsilon$ to make the decoding work

Why not cascade down to one node or just a few nodes? Probability that those nodes fail is too high.

Why stop at $kp^i=\sqrt{k}$? (1) At that point can decode in $O((\sqrt{k})^2)=O(k)$ time using RS. (2) For random erasures and small enough μ , with high probability at most an α fraction of bits at any level are missing

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Can fix $kp(1-\epsilon)$ random erasures