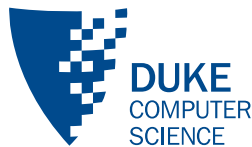


# Unsupervised Learning

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# Machine Learning

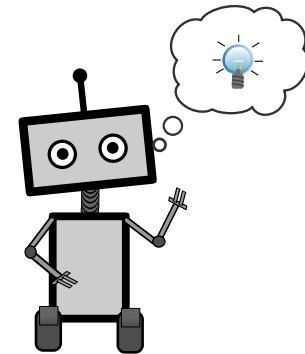


Subfield of AI concerned with *learning from data*.

Broadly, using:

- *Experience*
- To Improve *Performance*
- On Some *Task*

(Tom Mitchell, 1997)



# Unsupervised Learning



Input:

$X = \{x_1, \dots, x_n\}$  **inputs**

Try to understand the  
*structure of the data.*

*E.g., how many types of cars?  
How can they vary?*



# Clustering



One particular type of unsupervised learning:

- Split the data into discrete clusters.
- Assign new data points to each cluster.
- Clusters can be thought of as *types*.

**Formal definition**

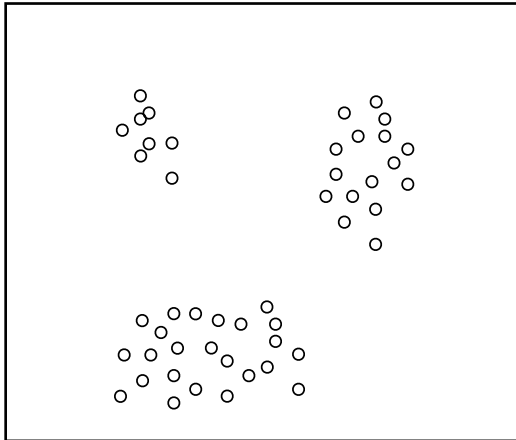
Given:

- Data points  $X = \{x_1, \dots, x_n\}$ ,

Find:

- Number of clusters  $k$
- Assignment function  $f(x) = \{1, \dots, k\}$

# Clustering



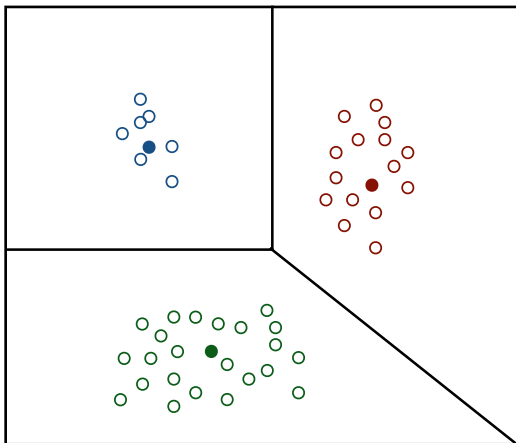
# k-Means



One approach:

- Pick  $k$
- Place  $k$  points (“means”) in the data
- Assign new point to  $i$ th cluster if nearest to  $i$ th “mean”.

# k-Means



# k-Means



Major question:

- *Where to put the “means”?*

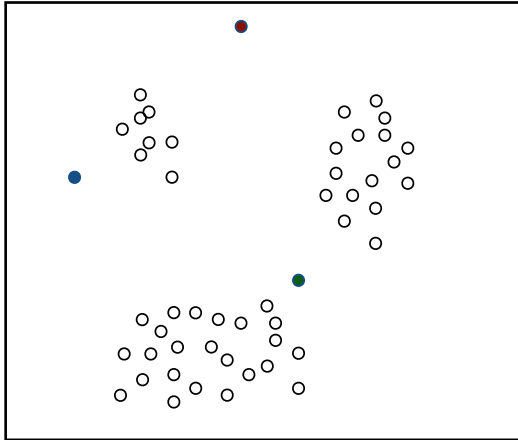
Very simple algorithm:

- Place  $k$  “means”  $\{\mu_1, \dots, \mu_k\}$  at random.
- Assign all points in the data to each “mean”  
 $f(x_j) = i$  such that  $d(x_j, \mu_i) \leq d(x_j, \mu_l) \forall l \neq i$

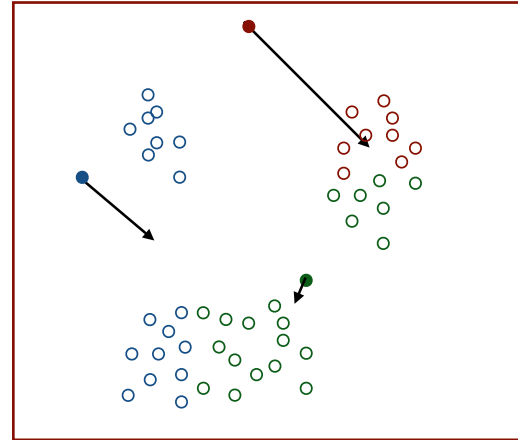
- Move “mean” to mean of assigned data.

$$\mu_i = \sum_{v \in C_i} \frac{x_v}{|C_i|}$$

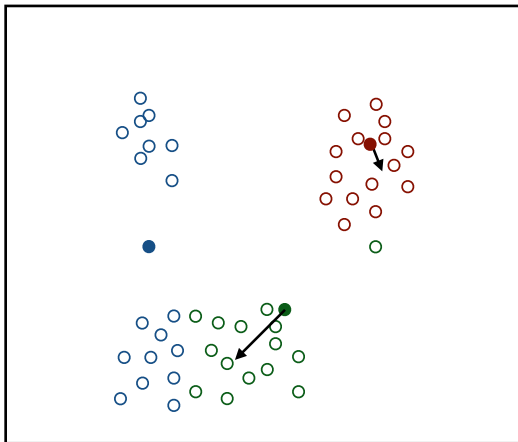
# k-Means



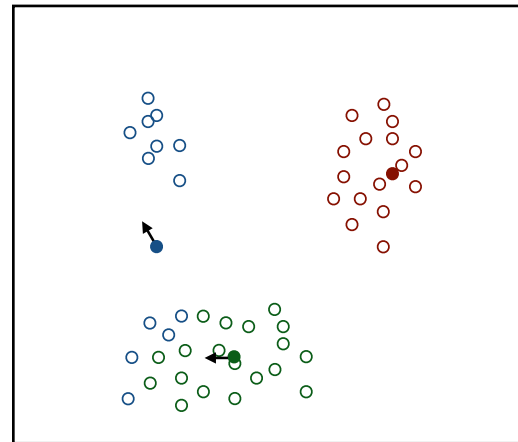
# k-Means



# k-Means



# k-Means



## k-Means



Remaining questions ...

How to choose  $k$ ?

What about bad initializations?

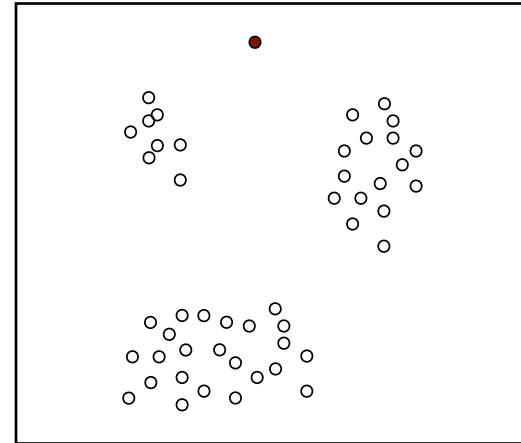
Broadly:

- Use a quality metric.
- Look through  $k$ .
- Random restart initial position.

## Density Estimation



Clustering: can answer *which cluster*, but not *does this belong?*



## Density Estimation



Estimate the *distribution the data is drawn from*.

This allows us to evaluate the probability that a new point is drawn from the same distribution as the old data.

**Formal definition**

Given:

- Data points  $X = \{x_1, \dots, x_n\}$ ,

Find:

- PDF  $P(X)$

## GMM



Simple approach:

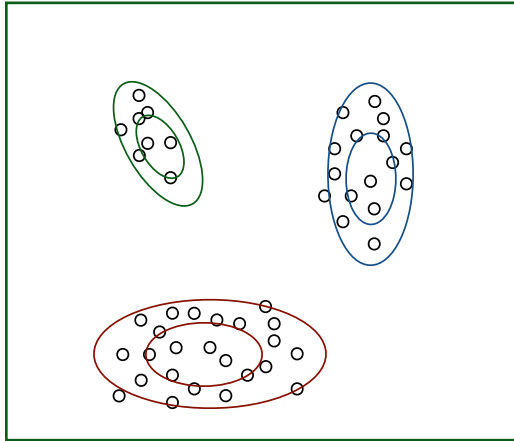
- Model the data as a mixture of Gaussians.

Each Gaussian has its own mean and variance.

Each has its own *weight* (sum to 1).

**Weighted sum of Gaussians still a PDF.**

# GMM



# GMM



Algorithm - broadly as before:

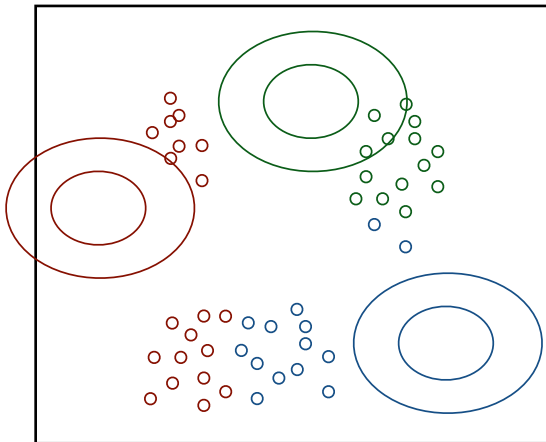
- Place  $k$  “means”  $\{\mu_1, \dots, \mu_k\}$  at random.
- Set variances to be high.
- Assign all points to highest probability distribution.

$$C_i = \{x_v | N(x_v | \mu_i, \sigma_i^2) > N(x_v | \mu_j, \sigma_j^2), \forall j\}$$

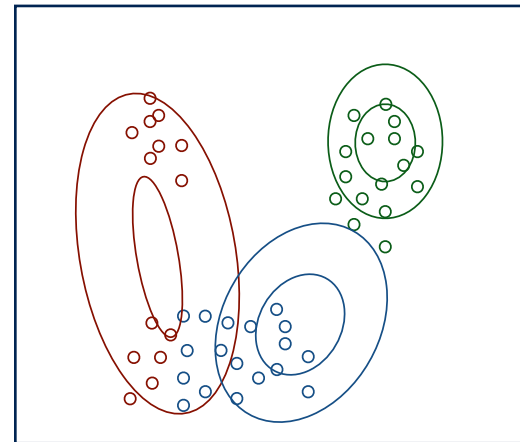
- Set mean, variance to match assigned data.

$$\mu_i = \sum_{v \in C_i} \frac{x_v}{|C_i|} \quad \sigma_i^2 = \text{variance}(C_i) \quad w_i = \frac{|C_i|}{\sum_j |C_j|}$$

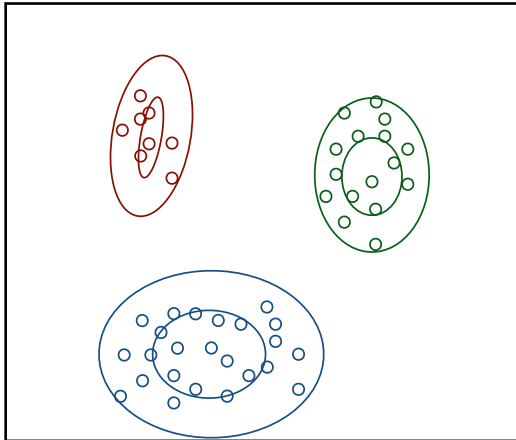
# GMM



# GMM



# GMM



# GMM



Major issue:

- How to decide between two GMMs?
- How to choose  $k$ ?

General statistical question: model selection.  
Several good answers for this.

Simple example: **Bayesian information criterion (BIC)**.  
Trades off model complexity ( $k$ ) with fit (likelihood).

$$-2 \log L + k \log n$$

likelihood                      # parameters in model                      # data points

# Application: Novelty Detection



Intrusion detection - when is a user behaving *unusually*?

First proposed by Prof. Dorothy Denning in 1986.  
(1995 ACM Fellow)

