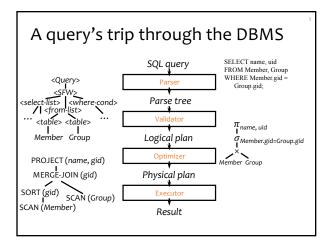
Query Processing: A Systems View

Introduction to Databases CompSci 316 Spring 2019



Announcements (Thu., Apr. 4)

- Monday 04/08: Hw4-problem 2 due
- Friday 04/12: HW4-problem 1 + this week's problem due
- Remember to submit project update on piazza tomorrow (Friday)



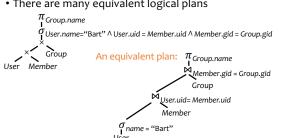
Parsing and validation

- Parser: SQL → parse tree
 - Detect and reject syntax errors
- Validator: parse tree → logical plan
 - Detect and reject semantic errors
 - · Nonexistent tables/views/columns?
 - · Insufficient access privileges?
 - · Type mismatches?
 - Examples: AVG(name), name + pop, User UNION Member
 - Also

 - Expand view definitions
 - Information required for semantic checking is found in system catalog (which contains all schema information)

Logical plan

- Nodes are logical operators (often relational algebra operators)
- There are many equivalent logical plans



Physical (execution) plan

- A complex guery may involve multiple tables and various query processing algorithms
 - E.g., table scan, index nested-loop join, sort-merge join, hash-based duplicate elimination...
- A physical plan for a query tells the DBMS query processor how to execute the query
 - A tree of physical plan operators
 - Each operator implements a query processing algorithm
 - Each operator accepts a number of input tables/streams and produces a single output table/stream

Examples of physical plans FROM User, Member, Group WHERE User.name = 'Bart' AND User.uid = Member.uid AND Member.gid = Group.gid; PROJECT (Group.name) PROJECT (Group.name) | MERGE-JOIN (gid) INDEX-NESTED-LOOP-JOIN (gid) Index on Group(gid) SCAN (Group) INDEX-NESTED-LOOP-JOIN (uid) MERGE-JOIN (uid) Index on Member(uid) FILTER (name = "Bart") INDEX-SCAN (name = "Bart") SCAN (Member) Index on User(name) SCAN (User) · Many physical plans for a single query • Equivalent results, but different costs and assumptions! TDBMS query optimizer picks the "best" possible physical plan

Physical plan execution

- How are intermediate results passed from child operators to parent operators?
 - · Temporary files
 - Compute the tree bottom-up
 - · Children write intermediate results to temporary files
 - Parents read temporary files
 - Iterators
 - Do not materialize intermediate results
 - Children pipeline their results to parents



Iterator interface

- Every physical operator maintains its own execution state and implements the following methods:
 - open(): Initialize state and get ready for processing
 - getNext(): Return the next tuple in the result (or a null pointer if there are no more tuples); adjust state to allow subsequent tuples to be obtained
 - close(): Clean up

An iterator for table scan

- State: a block of memory for buffering input *R*; a pointer to a tuple within the block
- open(): allocate a block of memory
- getNext()
 - If no block of R has been read yet, read the first block from the disk and return the first tuple in the block
 - Or null if R is empty
 - If there is no more tuple left in the current block, read the next block of *R* from the disk and return the first tuple in the block
 - Or null if there are no more blocks in R
 - Otherwise, return the next tuple in the memory block
- close(): deallocate the block of memory

An iterator for nested-loop join R: An iterator for the left subtree S: An iterator for the right subtree open() Ropen() Sopen() Sopen() Sopen() If s is hull; # no more tuple from S Schoes() # reopen S Schoes() # return null if for is hull; # no more tuple from R return null if former, s). Is this tuple-based or block-based nested-loop join?

An iterator for 2-pass merge sort

- - · Allocate a number of memory blocks for sorting
 - · Call open() on child iterator
- - If called for the first time
 - Call getNext() on child to fill all blocks, sort the tuples, and output a
 - Repeat until getNext() on child returns null
 - Read one block from each run into memory, and initialize pointers to point to the beginning tuple of each block
- Return the smallest tuple and advance the corresponding pointer; if a block is exhausted bring in the next block in the
- - · Call close() on child
 - Deallocate sorting memory and delete temporary runs

Blocking vs. non-blocking iterators

- A blocking iterator must call getNext() exhaustively (or nearly exhaustively) on its children before returning its first output tuple
 - Examples: sort, aggregation
- A non-blocking iterator expects to make only a few getNext() calls on its children before returning its first (or next) output tuple
 - Examples: dup-preserving projection, filter, merge join with sorted inputs

Execution of an iterator tree

- Call root.open()
- Call root.getNext() repeatedly until it returns null
- Call root.close()
- Requests go down the tree
- Intermediate result tuples go up the tree
- *No intermediate files are needed
 - But maybe useful if an iterator is opened many times
 - Example: complex inner iterator tree in a nested-loop join; "cache" its result in an intermediate file

Iterators are showing their age...

While iterators are an elegant way of pipelining execution, their implementation tends to be inefficient on modern architectures

- Too many (virtual) function calls
- Poor data locality—in memory instead of CPU registers
- Fail to take advantage of
 - · Compiler loop unrolling
 - · CPU pipelining
 - SIMD (single instruction, multiple data)

Which one do you think runs faster?



Whole-stage "codegen"

- Given a physical plan, fuse operators together to generate query-specific code, with loops instead of iterator function calls
- Instead of "interpreting" the physical plan, give generated code to an optimizing compiler
- Functionality of a general-purpose execution engine; performance as if system is hand-built to run your specific query
- This approach has been adopted by newer systems, such as Spark