

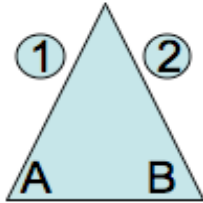
Name _____

Date _____

In the past 2 weeks we have worked on line following with one light sensor. This week we will move on to using 2 light sensors to follow lines.

The following is a chart designed to help you understand what's going on with the two light sensors.

The triangle represents the robot, and the black line is, you guessed it, the line.



1 & 2 are light sensors, A and B are motors

Complete the following chart with the values and actions necessary to make the robot follow the line

Value of		Action of	
Sensor 1	Sensor 2	Motor A	Motor B

