



# FAST DEFORMATION IMAGING FROM LIMITED-ANGLE PROJECTIONS IN RADIATION THERAPY

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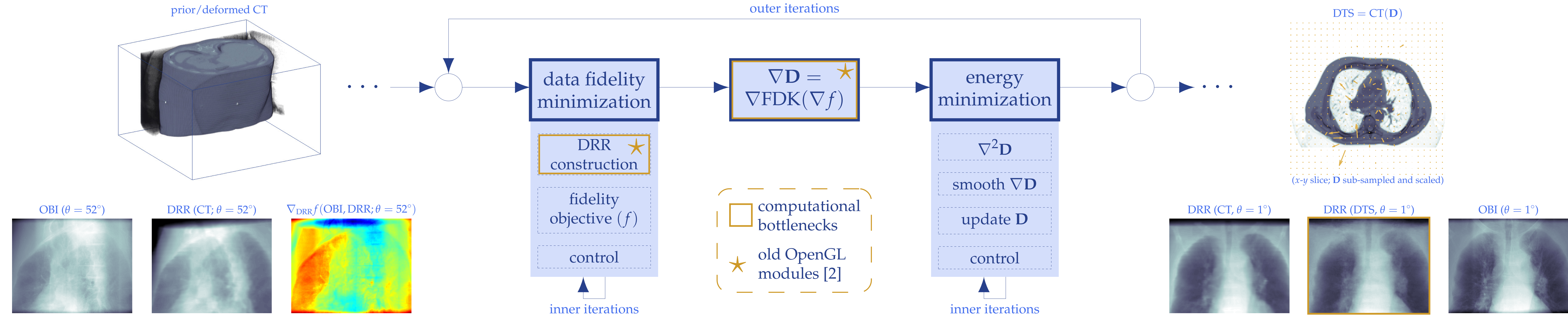
## Introduction

Image-guided radiation therapy is a major paradigm in cancer treatment, where on-board images (OBIs) may be used to monitor tumor motion and adjust radiation delivery.

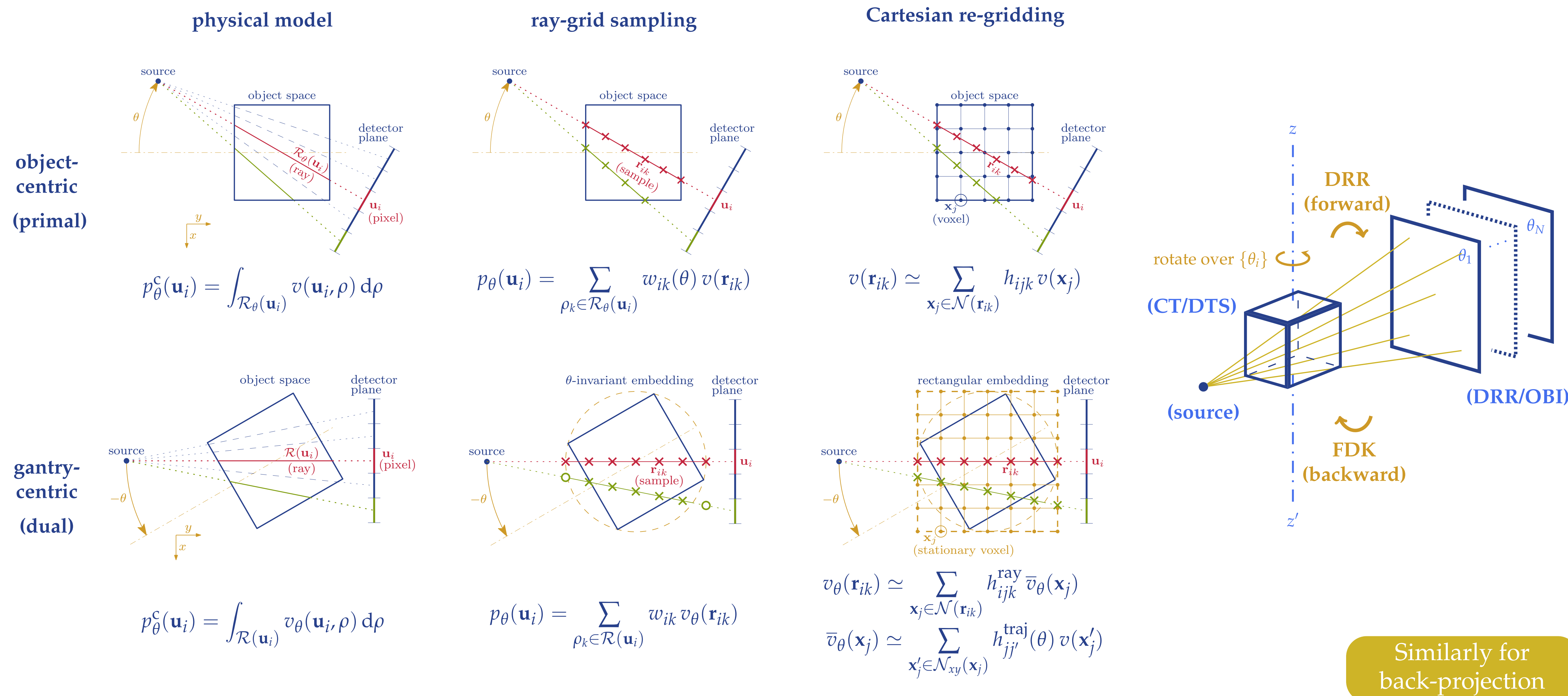
The LIVE system [1], developed at Duke University, may account for intrafraction motion via Digital Tomosynthesis (DTS) from a limited-angle OBI scan. This reduces imaging time and dose; however, DTS is performed through iterative deformable registration [3], which presents a challenge in meeting clinical response time requirements.

We propose a versatile model for the design and development of primitive operations for DTS. Its purpose is to facilitate (a) flexible composition and (b) high-performance numerical implementation of advanced DTS algorithms. We demonstrate our approach and its results for the case of LIVE.

## Digital tomosynthesis reconstruction scheme [3]



## Digital forward projection models: primal & dual



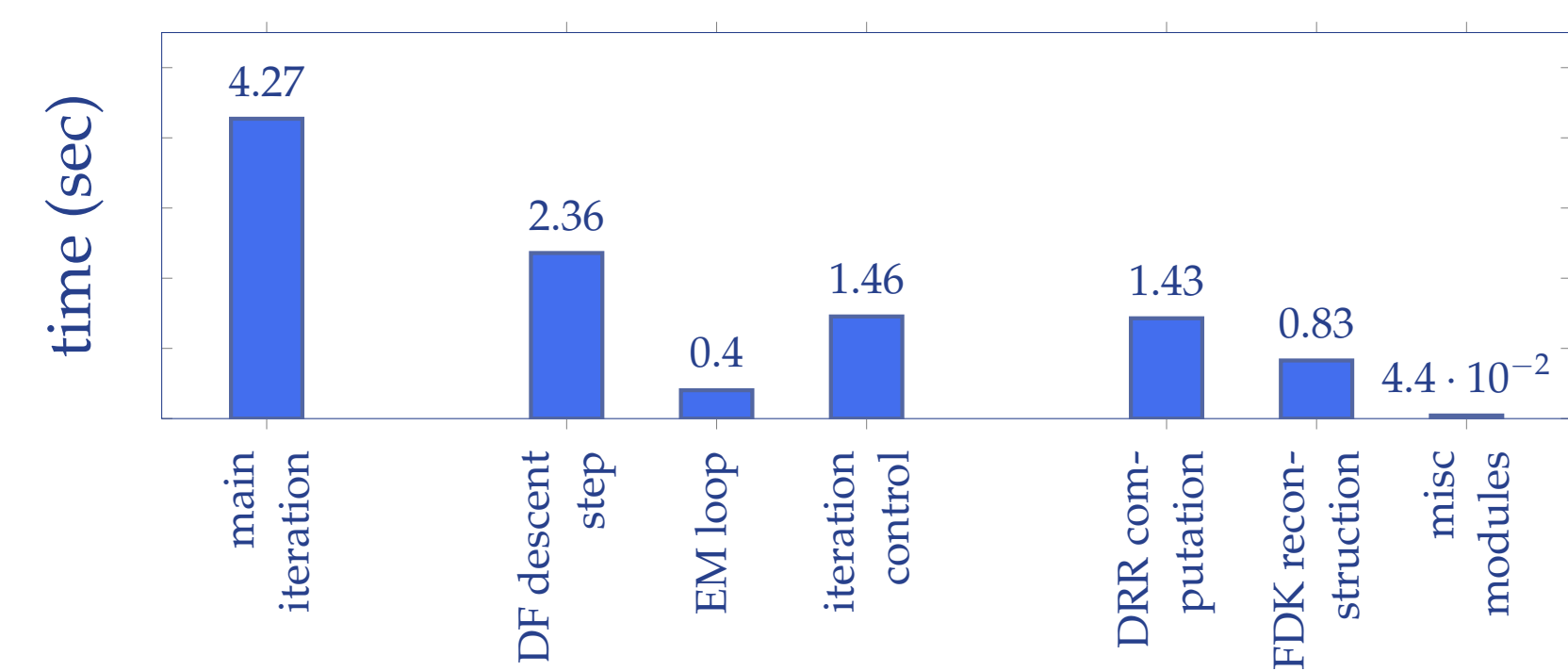
## Advantages

- Composition of digital operator weights—e.g. for DRR generation:
$$\mathbf{p}_\theta \simeq \mathbf{C}(\theta) \mathbf{M}(\theta) \mathbf{v}, \quad \text{or} \quad \mathbf{p}_\theta \simeq \mathbf{C}_{\text{ray}} \mathbf{M}_{\text{ray}} \bar{\mathbf{v}}_\theta, \quad \bar{\mathbf{v}}_\theta \simeq \left[ \left( \mathbf{C}_{\text{traj}}(\theta) \mathbf{M}_{\text{traj}}(\theta) \right) \otimes \mathbf{I}_z \right] \mathbf{v}$$
- Separation of static (geometric and numerical model) and dynamic (volume/detector data) processing:
  - $\mathbf{C}$  (composite coefficients) and  $\mathbf{M}$  (grid masks) may be pre-computed
  - only  $\mathbf{v}$  and  $\mathbf{p}_\theta$  vary across iterations
- Reduced space (memory) and time (# of operations) complexity with dual model:

Set	Model configuration					Space (GiB)		Time (GFLOP)		
	$\bar{\Omega}_v$	$\bar{\Omega}_p$	$ \Theta $	$ \mathcal{R}(\mathbf{u}) $	$\mathcal{N}(\mathbf{x})$	Primal	Dual	Primal	Dual	
A	256×256×160	512×384	30	256	2×2×2	45.2	1.2	23.0	9.8	
B	256×256×160	512×384	60	256	2×2×2	113.0	1.3	26.7	19.6	
C	256×256×160	512×384	60	256	6×6×6	244.2	3.4	805.6	206.1	
D	512×512×320	1024×768	60	512	2×2×2	903.8	10.0	213.4	157.0	

space-time complexities refer to both forward and backward projection operators, assuming all static data are pre-computed
- Efficiency and versatility:
  - Numerical accuracy (discrete weights model) decoupled from performance
  - Flexible mapping to computing architecture
  - Composable coefficients → modular, high-level implementations
  - Modest memory overhead
  - (Almost) same complexities for helical and saddle source trajectories

## Timing results



Total execution time (20 iterations):

- Previous: 1h30m [2, 3]
- Current: **1m25s** (60×)
- Target: < 2s (interactive)

Execution parameters:

- 3D volume (CT/DTS): 256 × 256 × 136
- 2D projections (OBI/DRR): 512 × 384
- # of projection angles: 62
- AMD Opteron 6168 & NVIDIA Tesla K20c

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## Key references

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