

# Overlays of Minimization Diagrams

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If  $F = \{f_i\}_{i=1}^n$  is a collection of  $n$  functions  $f_i : \mathbb{R}^d \rightarrow \mathbb{R}$ , the *lower envelope*  $\varepsilon_F(x) : \mathbb{R}^d \rightarrow \mathbb{R}$  is defined as

$$\varepsilon_F(x) = \min_{f_i \in F} f_i(x).$$

The *minimization diagram*  $\mathcal{M}_F$  of  $F$  is the orthogonal projection of the graph of  $\varepsilon_F$  onto  $\mathbb{R}^d$ .  $\mathcal{M}_F$  is a collection of maximal connected open faces of dimensions 0 to  $d$  such that for each open face  $\sigma$ ,  $\varepsilon_F$  restricted to  $\sigma$  is attained by a fixed subset of  $F$ .

The *overlay*  $\mathcal{Q}(F, G)$  of two minimization diagrams  $\mathcal{M}_F$  and  $\mathcal{M}_G$  is a collection of maximal connected open faces such that for each open face  $\sigma$ ,  $\varepsilon_F$  and  $\varepsilon_G$  restricted to  $\sigma$  is attained by a fixed subset of  $F$  and  $G$ . The *complexity* of the overlay is the number of such open faces.

I will present the following result by Koltun and Sharir [1]. If the graphs of  $F = \{f_i\}_{i=1}^n$  and  $G = \{g_i\}_{i=1}^n$  are collections of hyperplanes, then the complexity of  $\mathcal{Q}(F, G)$  is  $\Theta(n^{\lfloor d/2 \rfloor + 1})$ .

## References

- [1] Vladlen Koltun and Micha Sharir. On overlays and minimization diagrams. In *SCG '06: Proceedings of the twenty-second annual symposium on Computational geometry*, pages 395–401, New York, NY, USA, 2006. ACM Press.