JSPS Project on Molecular Computing

(presentation by Masami Hagiya)

- funded by Japan Society for Promotion of Science
- Research for the Future Program
 - biocomputing field chaired by Prof. Anzai
 - molecular computing
 - artificial cell (chemical IC)
 - evolutionary computation
 - input/output for molecular computing
 - complex systems
- October 1996 March 2001
 - 60M-80M yen per year

JSPS Project on Molecular Computing

- project leader Masami Hagiya (Computer Science)
- members
 - Takashi Yokomori (Computer Science)
 - Akira Suyama (Biophysics)
 - Yuzuru Husimi (Biophysics)
 - Kensaku Sakamoto (Biochemistry)
 - Shigeyuki Yokoyama (Biochemistry)
 - Masayuki Yamamura (Computer Science)
 - Masanori Arita (Genome Informatics)

Some Achievements

- Kensaku Sakamoto, Shigeyuki Yokoyama, and Masami Hagiya
 - Whiplash PCR
 - Hairpin Engine
- Masami Hagiya
 - VNA --- a simulator for DNA reactions
- Takashi Yokomori
 - Formal Models of DNA Computing
- Akira Suyama
 - Solid-based DNA Computing
 - Dynamic Programming DNA Computers
- Yuzuru Husimi
 - Evolutionary Reactor Based on 3SR
- Masayuki Yamamura
 - Aqueous Computing (with Tom Head)

DNA Computing

- Adleman-Lipton Paradigm A massive parallelism
 - random generation by assembly
 A combinatorial
 - selection by molecular biology experiments optimization
 large size A increase yield and decrease error
- one-pot reaction A
 autonomous computation A self-organization
 - DNA tiles by Winfree
 - DNA automata by Hagiya et al.
 - DNA boolean circuits by Ogihara and Ray
- theoretical analyses
 - complexity
 - formal languages

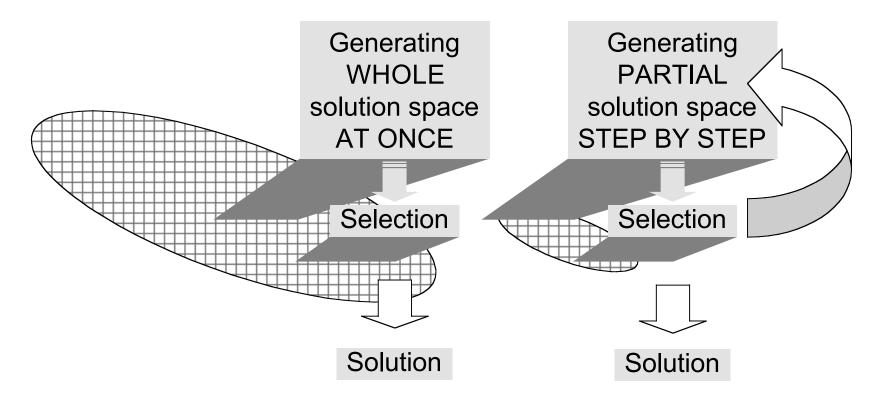
Brute Force v.s. Dynamic Programming DNA Computers

Brute Force

Large pool size Low reaction rate

Dynamic Programming

small pool size High reaction rate



3-CNF SAT Solution on DP DNA Computer

Problem : 4 variables, 10 clauses
$$(x_{1} \int x_{2} \int x_{3}) \mid (x_{1} \int \downarrow x_{2} \int x_{3}) \mid$$

$$(\downarrow x_{1} \int x_{2} \int \downarrow x_{3}) \mid (\downarrow x_{1} \int \downarrow x_{2} \int \downarrow x_{3}) \mid$$

$$(x_{1} \int \downarrow x_{3} \int \downarrow x_{4}) \mid (\downarrow x_{1} \int x_{2} \int \downarrow x_{4}) \mid$$

$$(\downarrow x_{1} \int x_{3} \int \downarrow x_{4}) \mid (x_{2} \int x_{3} \int x_{4}) \mid$$

$$(x_{2} \int \downarrow x_{3} \int x_{4}) \mid (\downarrow x_{2} \int \downarrow x_{3} \int x_{4})$$

Solution:

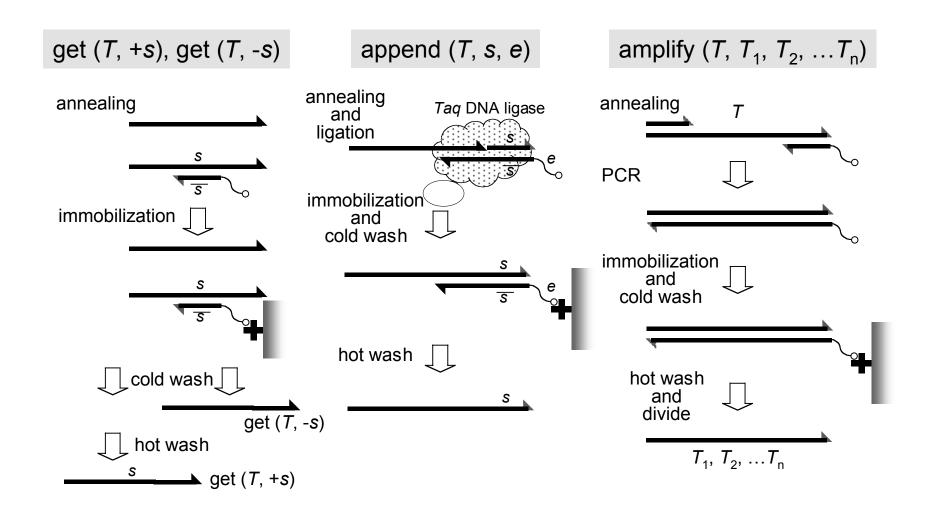
YES

$$\{X_1^T X_2^T X_3^F X_4^F\}$$

Basic Operations for Dynamic Programming DNA Computers

- get (T, +s), get (T, -s)get DNA molecules with a subsequence s (without s) in a tube T
- append (T, s, e)
 append a subsequence s at the end of DNA molecules with a splint e in a tube T
- merge $(T, T_1, T_2, ..., T_n)$ merge DNA molecules in tubes $T_1, T_2, ..., T_n$ into a tube T
- amplify $(T, T_1, T_2, ..., T_n)$ amplify DNA molecules in a tube T and divide them into tubes $T_1, T_2, ...,$ and T_n
- detect(T)
 detect DNA molecule in a tube T

Implementation of Basic Operations



DP algorithm for 3CNF-SAT on DNA Computers

```
procedure dna 3 sat (u_1, v_1, w_1, ..., u_m, v_m, w_m)
begin
   T_2^T = \{X_1^T X_2^T, X_1^F X_2^T\}; \text{ input } (T_2^T); T_2^T = \{X_1^T X_2^T, X_1^F X_2^T\}; \text{ input } (T_2^T);
   T_2^F = \{X_1^T X_2^F, X_1^F X_2^F\}; \text{ input } (T_2^F); T_2^F = \{X_1^T X_2^F, X_1^F X_2^F\}; \text{ input } (T_2^F);
   for k = 3 to n do
       merge(T_{v_i}^T, T_{k-1}^T, T_{k-1}^F); merge(T_{v_i}^F, T_{k-1}^T, T_{k-1}^F);
       for j = 1 to m do
          if w_i = 'x_k' then
              T_w^F = \text{getuvsat}(T_w^F, u_i, v_i);
           end
          if w_i = ' \downarrow x_k' then
              T_w^T = \text{getuvsat}(T_w^T, u_i, v_i);
           end
       end
       T^T = \operatorname{append}(T_{n}^T, X_k^T, \overline{X_{k+1}^{T/F} X_k^T}); \quad T^F = \operatorname{append}(T_{n}^F, X_k^F, \overline{X_{k+1}^{T/F} X_k^F});
       amplify(T^T, T_k^T, T_k^T); amplify(T^F, T_k^F, T_k^F);
   end
   output (\det(T_n));
end
```

```
procedure getuvsat (T, u, v)

begin

input (T);

T_u^T = get(T, + X_u^T); T_u^{IF} = get(T, -X_u^T);

T_u^F = get(T_u^{IF}, + X_u^F);

T_v^T = get(T_u^F, + X_v^T);

merge(T^T, T_u^T, T_v^T);

output (T^T);

end
```

Number of operations

$$n \leftarrow (2 \leftarrow \text{merge} + 2 \leftarrow \text{append} + 2 \leftarrow \text{amplify}) + 3m \leftarrow \text{get} + m \leftarrow \text{merge}$$

An Amount of DNA for Computation Brute Force v.s. Dynamic Programming

100 variable 3-CNF SAT

Adleman-Lipton's

Brute Force

DNA Computers

 $2x10^{12}$ g of dsDNA $1x10^{12}$ g of ssDNA

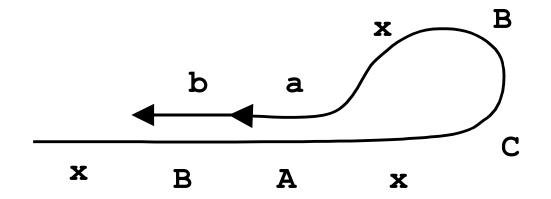
Dynamic Programming

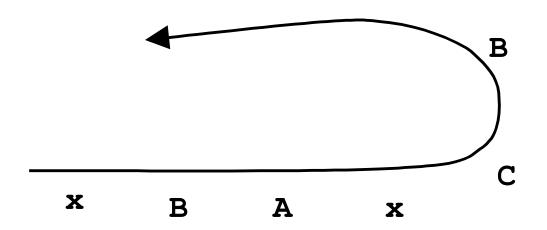
DNA Computers

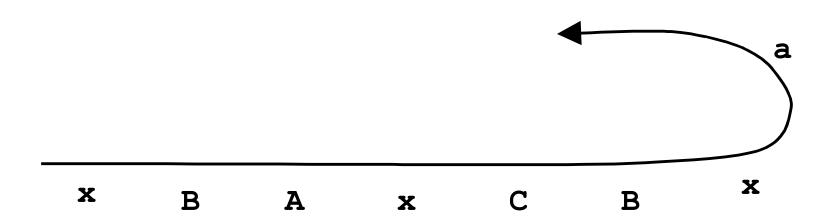
 $2x10^{-3}$ g of dsDNA (1x10⁻³ g of ssDNA)

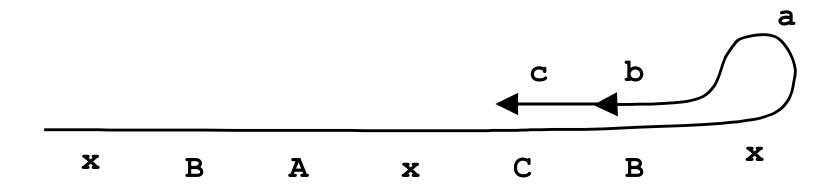
Autonomous Computation Self-Organization

- computational power of assembly (Winfree)
 - string _ regular
 - tree _ context-free
 - tile _ universal
- autonomous state transition (Hagiya et al.)
 - Whiplash PCR
- applications _ not only combinatorial optimization, but also
 - nanotechnology
 - genetic analysis









DNA State Machine

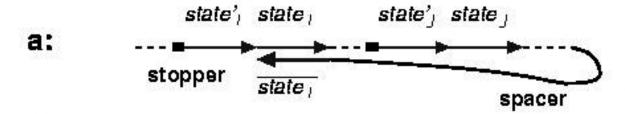
• Transition table:

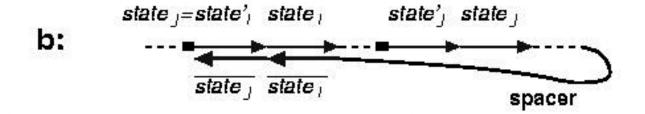
```
5'-stopper-state'_1-state_1-\cdots-stopper-state'_n-state_n-3' stopper: stopper: state'_i-state_i: state pair \begin{cases} state_i: \text{ state before transition} \\ state'_i: \text{ state after transition} \end{cases}
```

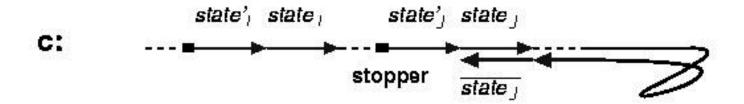
Current state:

 $5'-transition-table-\mathbf{spacer}-\overline{state_i}-3'$

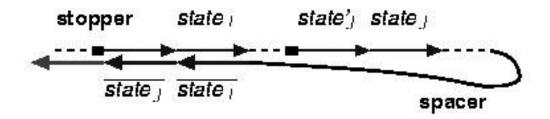
State Transitions by Polymerization







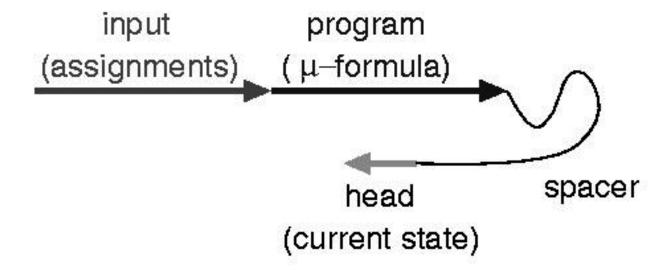
Polymerization Stop



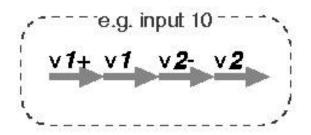
- States are encoded with three out of the four common deoxyribonucleotides (dATP, dGTP, dCTP and dTTP).
- A repetition of the missing deoxyribonucleotide works as a stopper sequence in polymerization.
- The polymerization buffer contains only complements of these three deoxyribonucleotides.

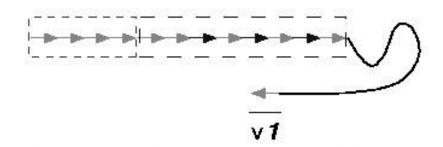
Evaluating Boolean μ -formulas

A μ -formula is a Boolean formula in which each input variable occurs at most once.



Encoding





VNA: Simulator for Virtual DNA

- a concrete computational model based on assembly and state transition
- abstract, but sufficiently physical bridging gaps between abstract models and real reactions molecule _ hybrid of virtual strands

abcd || CDEF

reactions

 hybridiza	ation	assembly

_	denaturation	decom	position

restriction	decomposition

ligationstate transition

self-hybridizationstate transition

extensionstate transition

VNA (cont.)

purposes

- verify feasibility of algorithms for DNA computing
- verify validity of molecular biology experiments (e.g., PCR experiments)
- parameter fitting in molecular biology experiments

examples

- Ogihara and Ray's computation of boolean circuits
- Winfree's construction of double-crossover units
- PCR experiments

• implementation

Java Å executable as an applet

VNA (cont.)

unify

- methods
 - combinatorial enumeration
 - continuous simulation (diff. eq.)
- avoiding combinatorial explosion contributions in simulation technology
 - threshold
 - stochastic
- parameter fitting by GA
 - optimizing amplification in PCR experiments

Goals of Molecular Computing concluding remark

- analysis of computational power of biomolecules
 - understanding life
 - origin of life
 - wet artificial life
 - engineering applications
 - combinatorial optimization
 - nanotechnology
 - genetic analysis
- new computational models Å simulation technology digital Å analog Å physical