

DNA Nanorobotics

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DNA Nanorobotics

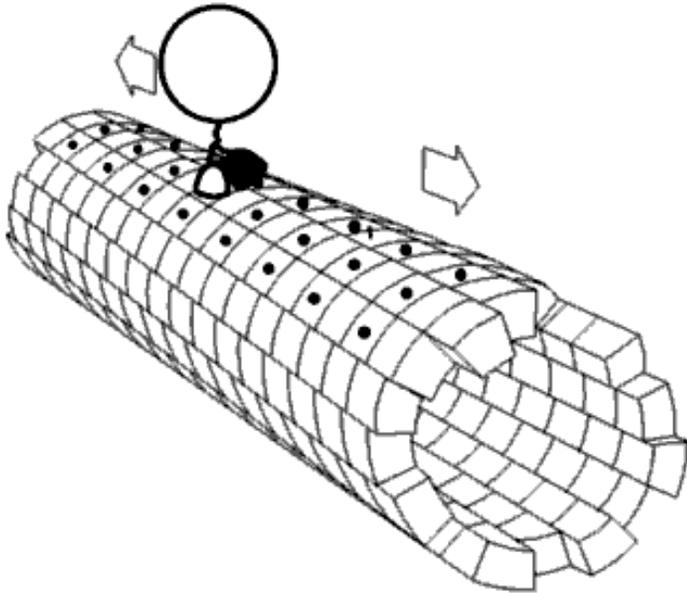
Book Chapter: Chandran, H., Gopalkrishnan, N., & Reif, J. (n.d.). DNA Nanorobotics.

Aim: design and fabrication of dynamic DNA nanostructures that perform specific tasks via a series of state changes (average system behavior)

Challenges

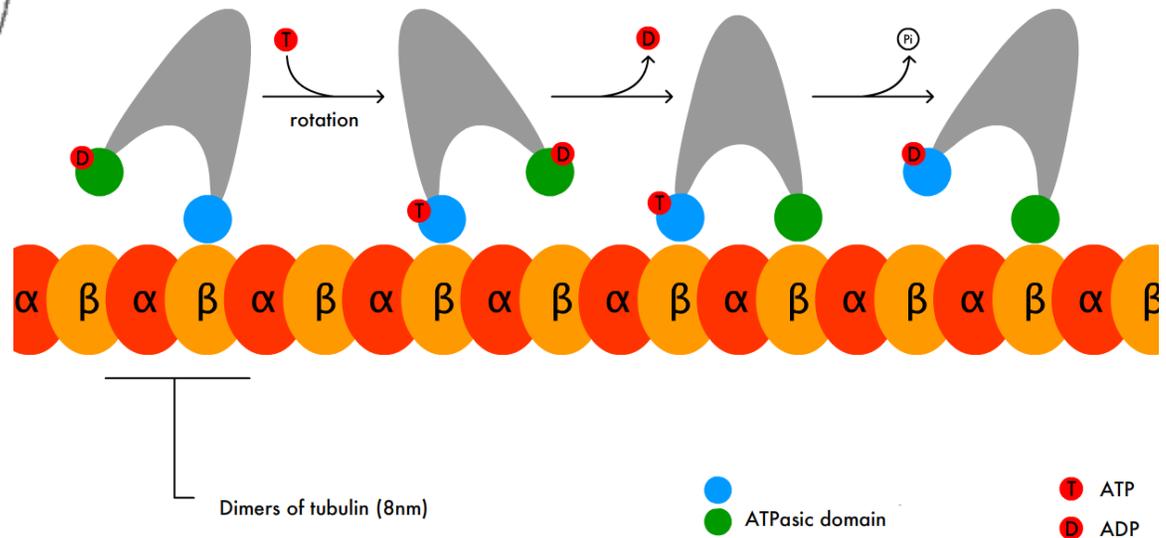
1. Domain to sequence mapping in design (spurious interactions)
 2. Fuel (spontaneous entropic effects)
 3. Assembly + purification
 4. Experimental design for validation
- ...each step is a challenge

Examples in Nature → Kinesins



ATPases (ATP → ADP → energy)

Motility of kinesin



Yildiz, A. (2004). Kinesin Walks Hand-Over-Hand. *Science*, 303 (5658), 676–678. doi:10.1126/science.1093753

Book Chapter: Chandran, H., Gopalkrishnan, N., & Reif, J. (n.d.). DNA Nanorobotics.

Examples in Nature → Myosins

<http://www.dnatube.com/video/389/A-Moving-Myosin-Motor-Protein>

<http://www.youtube.com/watch?v=gJ309LfHQ3M>

Toyoshima, Y. Y., Kron, S. J., McNally, E. M., Niebling, K. R., Toyoshima, C., & Spudich, J. A. (1987). Myosin subfragment-1 is sufficient to move actin filaments in vitro.

Binds to actin → ATP hydrolysis → mechanical movement

Why DNA?

Design

1. Predictable geometries can be achieved
2. Can predict dsDNA thermodynamics + geometry using software
3. Software-assisted design

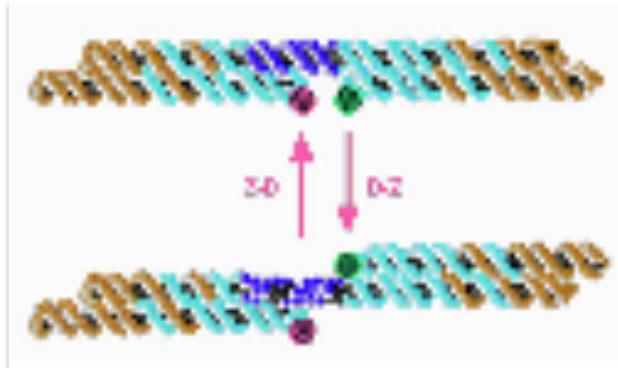
Why DNA?

Experiments

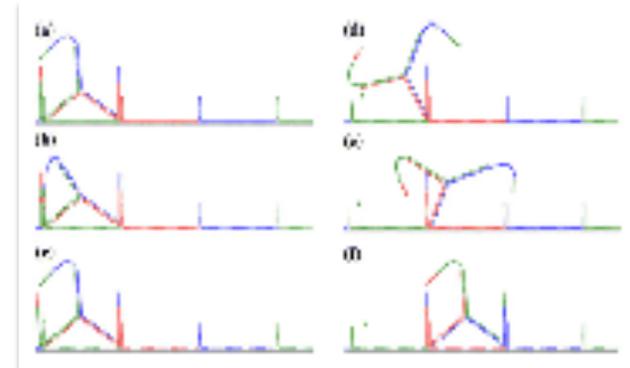
1. Custom ssDNA synthesis
→ routine + inexpensive
2. Assembly simple
3. Characterization techniques (AFM, TEM, ...)

Chapter Classification

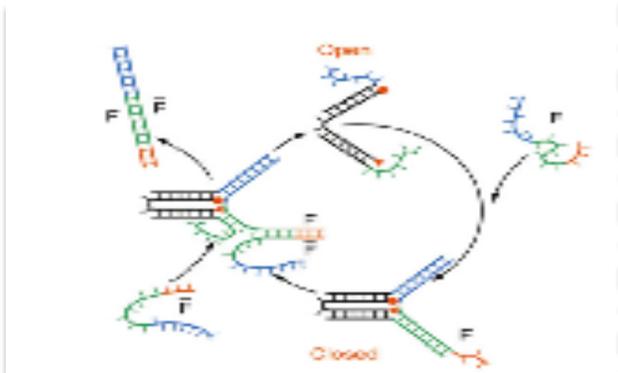
Switch conformation based on environment



Powered by enzymatic reactions



Hybridization reactions



Programmable

