Markov Chains

Markov chains:

- Powerful tool for sampling from complicated distributions
- rely only on local moves to explore state space.
- Many use Markov chains to *model* events that *arise* in nature.
- We create Markov chains to explore and sample from problems.

2SAT:

- Fix some assignment A
- let f(k) be expected time to get all n variables to match A if n currently match.
- Then f(n) = 0, f(0) = 1 + f(1), and $f(k) = 1 + \frac{1}{2}(f(k+1) + f(k-1))$.
- Rewrite: f(0) f(1) = 1 and f(k) f(k+1) = 2 + f(k-1) f(k)
- So f(k) f(k-1) = 2k+1
- deduce $f(0) = 1 + 3 + \dots + (2n 1) = n^2$
- so, find with probability 1/2 in $2n^2$ time.
- With high probability, find in $O(n^2 \log n)$.

More general formulation: Markov chain

- State space S
- markov chain begins in a start state X_0 , moves from state to state, so output of chain is a sequence of states $X_0, X_1, \ldots = \{X_t\}_{t=0}^{\infty}$
- movement controlled by matrix of *transition probabilities* p_{ij} = probability next state will be j given current is i.
- thus, $\sum_{i} p_{ij} = 1$ for every $i \in S$
- implicit in definition is *memorylessness property*:

 $\Pr[X_{t+1} = j \mid X_0 = i_0, X_1 = i_1, \dots, X_t = i] = \Pr[X_{t+1} = j \mid X_t = i] = p_{ij}.$

- Initial state X_0 can come from any probability distribution, or might be fixes (trivial prob. dist.)
- Dist for X_0 leads to dist over sequences $\{X_t\}$
- Suppose X_t has distribution q (vector, q_i is prob. of state i). Then X_{t+1} has dist qP. Why?

• Observe $\Pr[X_{t+r} = j \mid X_t = i] = P_{ij}^r$

Graph of MC:

- Vertex for every state
- Edge (i, j) if $p_{ij} > 0$
- Edge weight p_{ij}
- weighted outdegree 1
- Possible state sequences are paths through the graph

Stationary distribution:

- a π such that $\pi P = \pi$
- left eigenvector, eigenvalue 1
- steady state behavior of chain: if in stationary, stay there.
- note stationary distribution is a sample from state space, so if can get right stationary distribution, can sample
- lots of chains have them.
- to say which, need definitions.

Things to rule out:

- disconnected graph
- infinite directed line
- 2-cycle

Irreducibility

- any state can each any other state
- i.e. path between any two states
- i.e. single strong component in graph

Persistence/Transience:

- $r_{ij}^{(t)}$ is probability first hit state j at t, given start state i.
- f_{ij} is probability eventually reach j from i, so $\sum r_{ij}^{(t)}$
- expected time to reach is hitting time $h_{ij} = \sum t r_{ij}^{(t)}$

- If $f_{ij} < 1$ then $h_{ij} = \infty$ since might never reach. Converse not always true.
- If $f_{ii} < 1$, state is transient. Else persistent. If $h_{ii} = \infty$, null persistent.

Periodicity:

- Periodicity of a state is max T such that some state only has nonzero probability at times a + Ti for integer i
- Chain *periodic* if some state has periodicity > 1
- In graph, all cycles containing state have length multiple of T
- Easy to eliminate: add self loops
- slows down chain, otherwise same

Ergodic:

- aperiodic and non-null persistent
- means might be in state at any time in (sufficiently far) future

Fundamental Theorem of Markov chains: Any irreducible, finite, aperiodic Markov chain satisfies:

- All states ergodic (none transient)
- unique stationary distribution π , with all $\pi_i > 0$
- $f_{ii} = 1$ and $h_{ii} = 1/\pi_i$
- number of times visit i in t steps approaches $t\pi_i$ in limit of t.

Justify all except uniqueness here. Finite irreducible aperiodic implies ergodic

- graph has strong components
- *final* strong component has no outgoing edges
- once leave nonfinal component, cannot return
- If two vertices in same strong component, have path between them
- so nonzero probability of reaching in (say) n steps.
- if nonfinal, nonzero probability of leaving in n steps.
- so, vertices in nonfinal components are transient
- if final, will eventually reach every vertex

- so, vertices in final components are persistent
- geometric distribution on time to reach, so expected time finite. Not null-persistent
- Thus: If number of states finite, no null persistent states.
- Markov chain *ireducible* if graph is one strong component.
- so all states persistent.

Intuitions for quantities:

- h_{ii} is expected return time
- So hit every $1/h_{ii}$ steps on average
- So $h_{ii} = 1/\pi_i$
- If in stationary dist, $t\pi_i$ visits follows from linearity of expectation

Random walks on undirected graphs:

- general Markov chains are directed graphs. But undirected have some very nice properties.
- take a connected, non-bipartite undirected graph on n vertices
- states are vertices.
- move to uniformly chosen neighber.
- So $p_{uv} = 1/d(u)$ for every neighbor v
- stationary distribution: $\pi_v = d(v)/2m$
- unqiqueness says this is only one
- deduce $h_{vv} = 2m/d(v)$

Definitions:

- Hitting time h_{uv} is expected time to reach u from v
- commute time is $h_{uv} + h_{vu}$
- $C_u(G)$ is expected time to visit all vertices of G, starting at u
- cover time is $\max_u C_u(G)$ (so in fact is max over any starting distribution).
- let's analyze max cover time

Examples:

- clique: commute time n, cover time $\Theta(n \log n)$
- line: commute time betweek ends is $\Theta(n^2)$
- lollipop: $h_{uv} = \Theta(n^3)$ while $h_{vu} = \Theta(n^2)$ (big difference!)
- also note: lollipop has edges added to line, but higher cover time: adding edges can increase cover time even though improves connectivity.

general graphs: adjacent vertices:

- lemma: for adjcaent (u, v), $h_{uv} + h_{vu} \leq 2m$
- proof: new markov chain on edge traversed following vertex MC
 - transition matrix is *doubly stochastic:* column sums are 1 (exactly d(v) edges can transit to edge (v, w), each does so with probability 1/d(v))
 - In homework, show such matrices have uniform stationary distribution.
 - Deduce $\pi_e = 1/2m$. Thus $h_{ee} = 2m$.
- So consider suppose original chain on vertex v.
 - suppose arrived via (u, v)
 - expected to traverse (u, v) again in 2m steps
 - at this point will have commuted u to v and back.
 - so conditioning on arrival method, commute time 2m (thanks to memorylessness)

General graph cover time:

- theorem: cover time O(mn)
- proof: find a spanning tree
- consider a dfs of tree-crosses each edge once in each direction, gives order v_1, \ldots, v_{2n-1}
- time for the vertices to be visited in this order is upper bounded by commute time
- but vertices adjacent, so commute times O(m)
- total time O(mn)
- tight for lollipop, loose for line.

Tighter analysis:

- analogue with electrical networks
 - Assume unit edge resistance
 - Kirchoff's law: current (rate of transitions) conservation

- Ohm's law
- Gives effective resistance R_{uv} between two vertices.
- Theorem: $C_{uv} = 2mR_{uv}$
- (tightens previous theorem, since $R_{uv} \leq 1$)
- Proof:
 - Suppose put d(x) amperes into every x, remove 2m from v
 - $-\phi_{uv}$ voltage at u with respect to v
 - Ohm: Current from u to w is $\phi_{uv} \phi_{wv}$
 - Kirchoff: $d(u) = \sum_{w \in N(u)} \phi_{uv} \phi_{wv} = d(u)\phi_{uv} \sum \phi_{wv}$
 - Also, $h_{uv} = \sum (1/d(u))(1 + h_{wv})$
 - same soln to both linear equations, so $\phi_{uv} = h_{uv}$
 - By same arg, h_{vu} is voltage at v wrt u, if insert 2m at u and remove d(x) from every x
 - add linear systems, find $h_{uv} + h_{vu}$ is voltage difference when insert 2m at u and remove at v.
 - now apply ohm.

Applications

Testing graph connectivity in logspace.

- Deterministic algorithm (matrix squaring) gives $\log^2 n$ space
- Smarter algorithms gives $\log^{4/3} n$ space
- $\log n$ open
- Randomized logspace achieves one-sided error

universal traversal sequences.

- Define labelled graph
- UTS covers any labelled graph
- deterministic construction known for cycle only
- we showed cover time $O(n^3)$
- so probability takes more than $2n^3$ to cover is 1/2
- repeat k times. Prob fail $1/2^k$

- How many graphs? $(nd)^O(nd)$
- So set $k = O(nd \log nd)$
- $\bullet\,$ probabilistic method