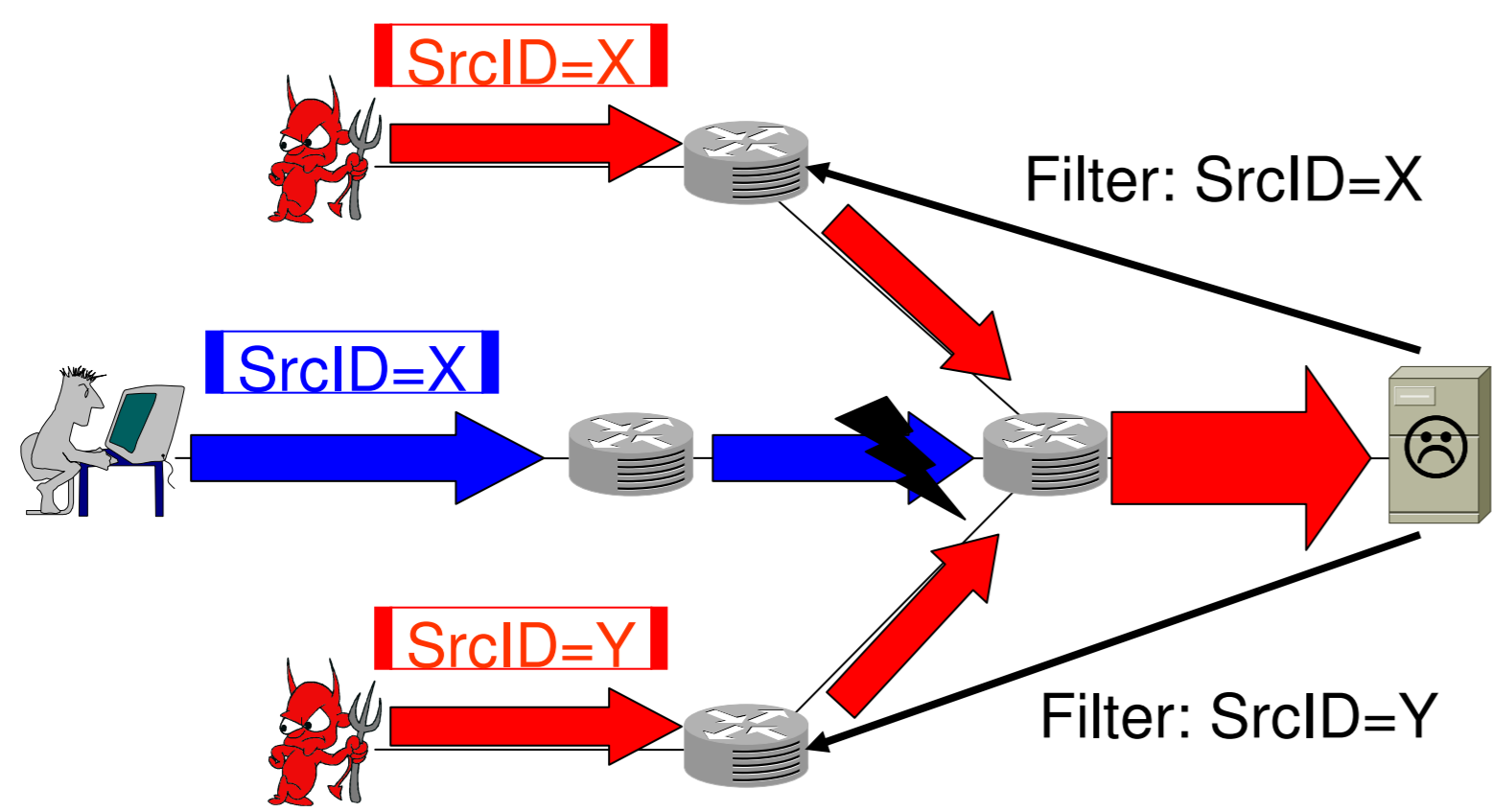


# Unspoofable Source Identifiers without Global Trust

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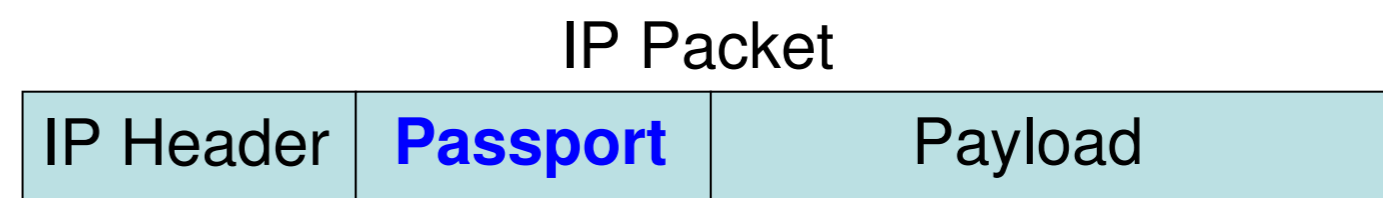
## Motivation



### Benefits:

- Providing unspoofable packet signatures for filtering
- Providing unspoofable identifiers for fair resource allocation
- Limiting reflector attack
- Useful for deterring future attacks

## Solution: Packet Passport



Every packet carries a passport, and packets with invalid passports are dropped or demoted.

## Key Features

- An attacker **cannot forge** valid passports.
- It is **efficient** to generate and verify passports at packet forwarding time.
- The passport system is **scalable** and **robust** against DoS attacks.
- The passport system supports **incremental deployment** and provides **incentives for early adoption**.

## Previous Solutions to Packet Source Identification

### Fast but weak:

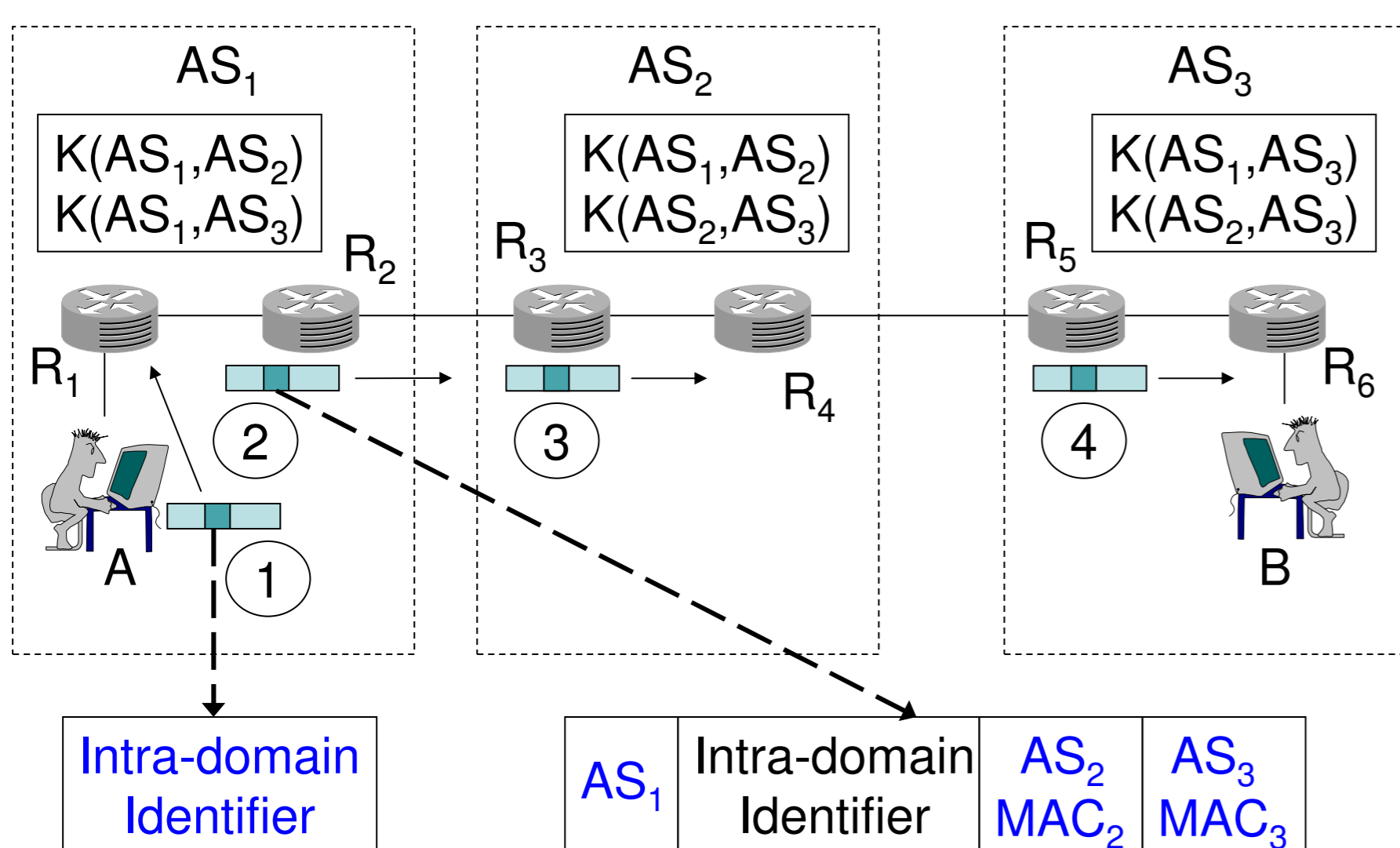
- *Ingress/egress filtering*: Source address is not verifiable.
- *Path Identifier* [Yaar03] & *AITF* [Argyaki05]: Part of a path identifier is spoofable.
- *Authenticated Marking Scheme* [Song01]: The path identifier is not verifiable at packet forwarding time.

- *Spoofing Prevention Method* [Anat05]: The secrets are transmitted in plain text, and there is no secret exchange protocol.

### Strong but inefficient and unscalable:

- *R.Perlman's PhD Thesis* [Perlman88]: Public key signatures are in packets to identify their sources.

## Passport Processing



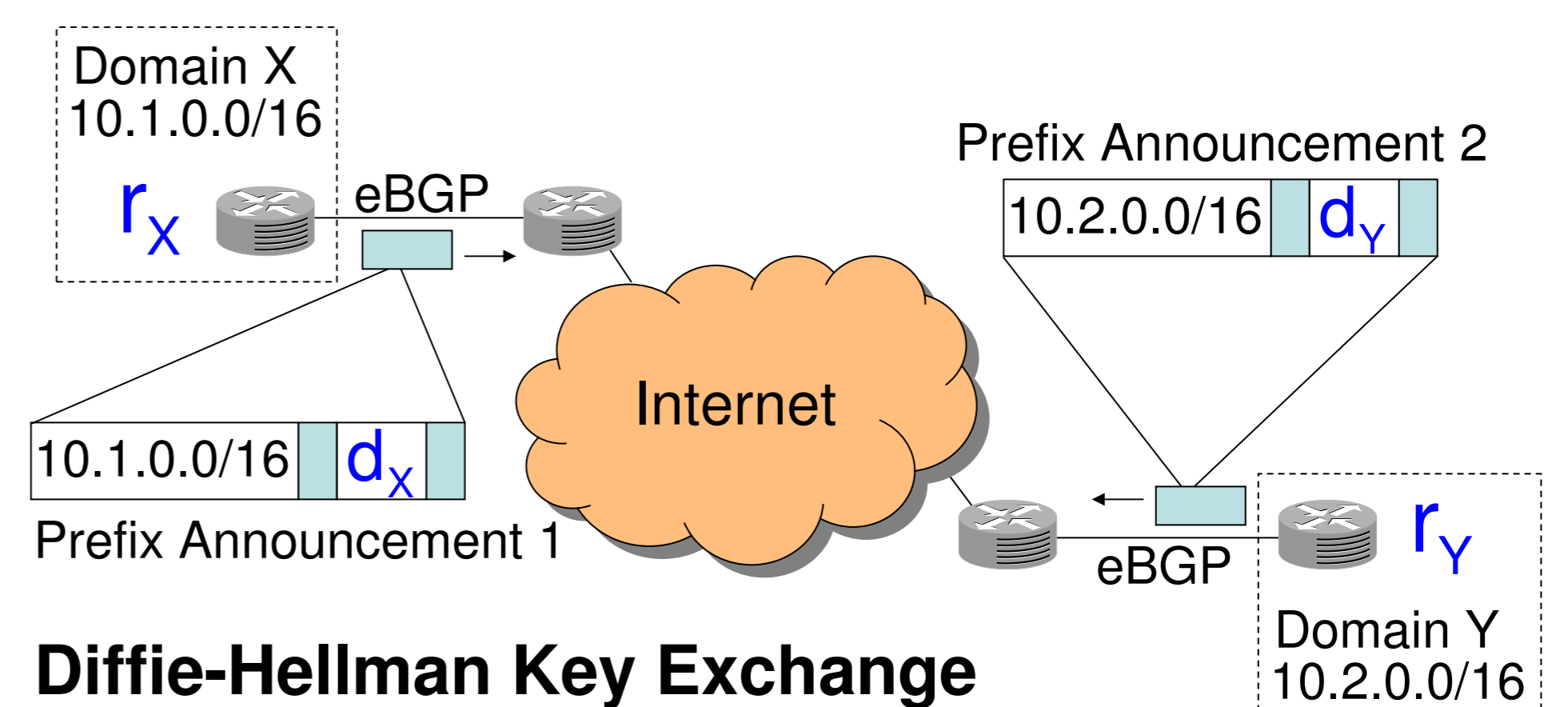
**MAC:** Message Authentication Code

$$\text{MAC}_x = \text{MAC}_{K(\text{AS}_1, \text{AS}_x)}(\text{AS}_1, \text{AS}_2, \text{AS}_3, \text{SrcIP}, \text{DstIP}, \dots)$$

**K(X, Y):** Symmetric key shared between two domains X and Y

- ① Intra-domain identifier is inserted.
- ② Intra-domain identifier is verified & full passport is inserted.
- ③  $\text{MAC}_2$  is verified using the key  $K(\text{AS}_1, \text{AS}_2)$ .
- ④  $\text{MAC}_3$  is verified using the key  $K(\text{AS}_1, \text{AS}_3)$ .

## Key Distribution



### Diffie-Hellman Key Exchange

$$d_x = g^{r_x} \text{ mod } p$$

$$d_y = g^{r_y} \text{ mod } p$$

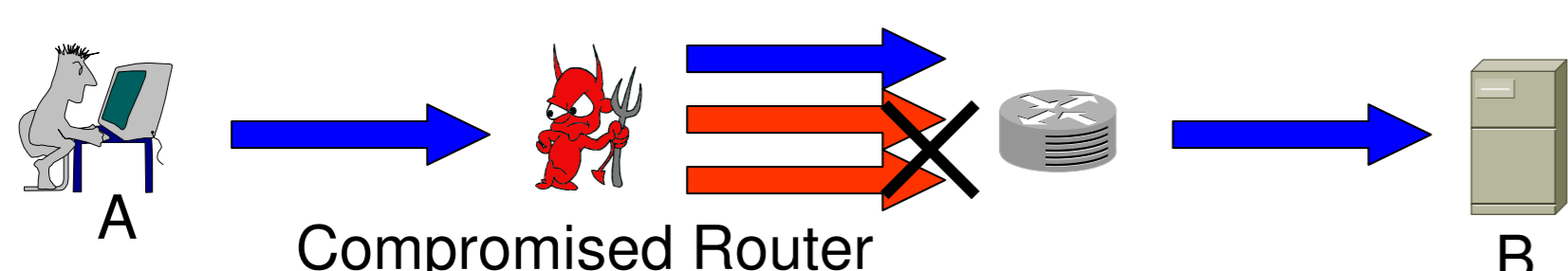
$$K(X, Y) = d_x^{r_y} \text{ mod } p = d_y^{r_x} \text{ mod } p$$

## Preliminary Evaluation

### Practical with today's hardware technology

- Passport generation & verification: with UMAC, a commodity PC can generate 975K passports and verify 3.9M passports per second.
- Key distribution: computation, communication and storage costs are negligible.
- Bloom filter: 16MB SRAM can "remember" 2.5Gbps traffic for 5 seconds with a false positive rate of  $5.7 \times 10^{-6}$ .

## Preventing Replay Attack



**Problem:** Attack sources cannot be identified.

- Solution:**
- Using *bloom filters* to detect passport duplication
  - Using *fast-rekeying* to deal with bloom filter flushing

**For details, please visit:**

<http://nds.ics.uci.edu/pktpassport>