Sampling from Databases

CompSci 590.02 Instructor: AshwinMachanavajjhala



Recap

- Given a set of elements, random sampling when number of elements N is known is easy if you have random access to any arbitrary element
 - Pick n indexes at random from 1 ... N
 - Read the corresponding n elements
- Reservoir Sampling: If N is unknown, or if you are only allowed sequential access to the data
 - Read elements one at a time. Include tth element into a reservoir of size n with probability n/t.
 - Need to access at most n(1+ln(N/n)) elements to get a sample of size n
 - Optimal for any reservoir based algorithm



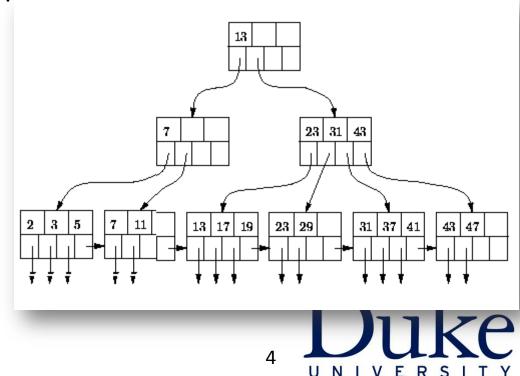
Today's Class

- In general, sampling from a database where elements are only accessed using indexes.
 - B⁺-Trees
 - Nearest neighbor indexes
- Estimating the number of restaurants in Google Places.



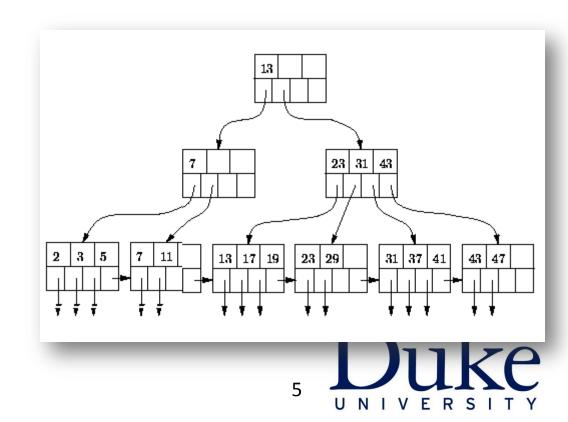
B+ Tree

- Data values only appear in the leaves
- Internal nodes only contain keys
- Each node has between $f_{max}/2$ and f_{max} children
 - f_{max} = maximum fan-out of the tree
- Root has 2 or more children



Problem

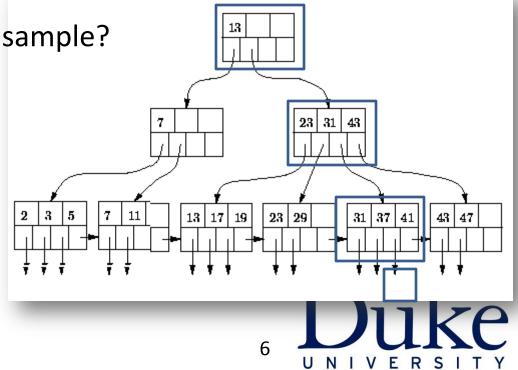
• How to pick an element uniformly at random from the B⁺ Tree?



Attempt 1: Random Path

Choose a random path

- Start from the root
- Choose a child uniformly at random
- Uniformly sample from the resulting leaf node
- Will this result in a random sample?

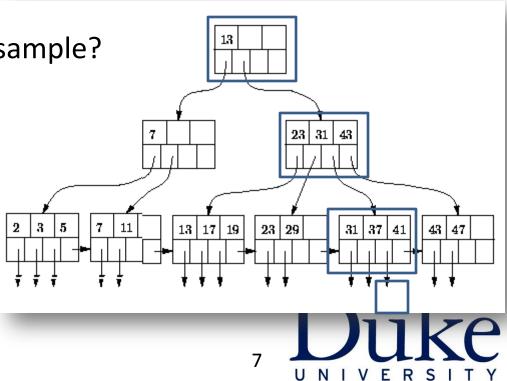


Attempt 1: Random Path

Choose a random path

- Start from the root
- Choose a child uniformly at random
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- Will this result in a random sample?

NO. *Elements reachable from internal nodes with low fanout are more likely.*



Attempt 2 : Random Path with Rejection

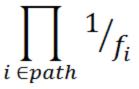
- Attempt 1 will work if all internal nodes have the same fan-out
- Choose a random path
 - Start from the root
 - Choose a child uniformly at random
 - Uniformly sample from the resulting leaf node
- Accept the sample with probability $\prod_{i \in path} \frac{f_i}{f_{max}}$



Attempt 2 : Correctness

• Any root to leaf path is picked with probability: $\prod_{i \in path} \frac{f_i}{f_{max}}$

• The probability of including a record given the path:



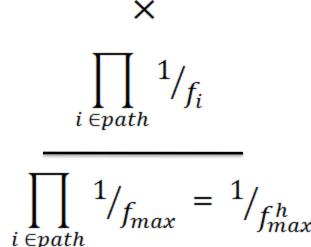


Attempt 2 : Correctness

• Any root to leaf path is picked with probability: $\prod_{i \in path}$

- The probability of including a record given the path:
- The probability of including a record:





 $f_{i/f_{max}}$

Attempt 3 : Early Abort

Idea: Perform acceptance/rejection test at each node.

- Start from the root
- Choose a child uniformly at random
- Continue the traversal with probability: f_i/f_{max}
- At the leaf, pick an element uniformly at random, and accept it with probability :

of elements in leaf max # elements in leaf

Proof of correctness: same as previous algorithm



Attempt 4: Batch Sampling

 Repeatedly sampling *n* elements will require accessing the internal nodes many times.



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Perform random walks simultaneously:

- At the root node, assign each of the n samples to one of its children uniformly at random
 - − n → (n₁, n₂, ..., n_k)
- At each internal node,
 - Divide incoming samples uniformly across children.
- Each leaf node receives *s* samples. Include each sample with acceptance probability $\prod_{i=1}^{n} f_{i+1}$

i ∈path



Attempt 4 : Batch Sampling

• Problem: If we start the algorithm with n, we might end up with fewer than n samples (due to rejection)



Attempt 4 : Batch Sampling

- Problem: If we start the algorithm with n, we might end up with fewer than n samples (due to rejection)
- Solution: Start with a larger set
- $n' = n/\beta^{h-1}$, where β is the ratio of average fanout and f_{max}

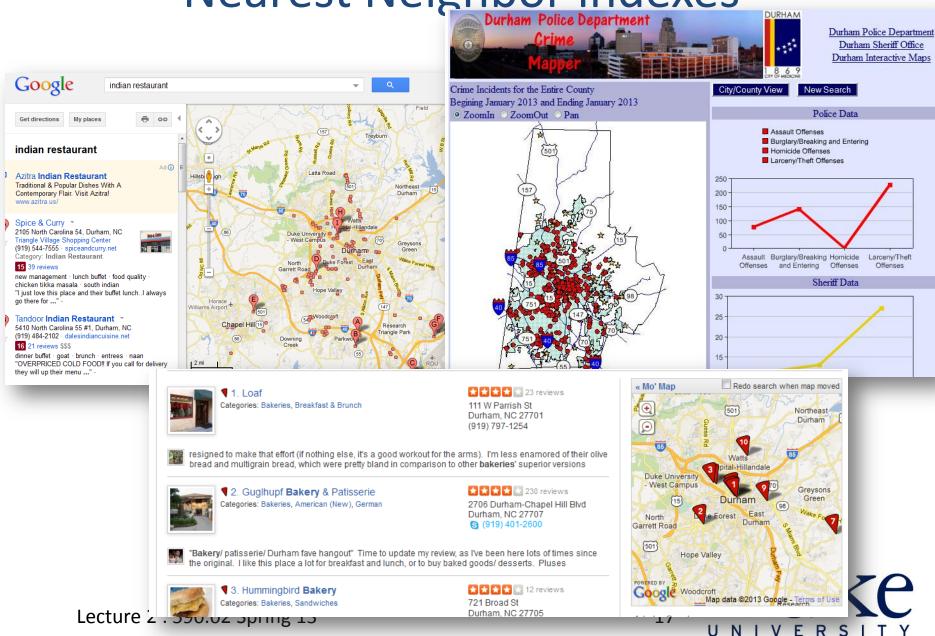


Summary of B⁺tree sampling

- Randomly choosing a path weights elements differently
 - Elements in the subtree rooted at nodes with lower fan-out are more likely to be picked than those under higher fan-out internal nodes
- Accept/Reject sampling helps remove this bias.



Nearest Neighbor indexes



Problem Statement

Input:

- A database D that can't be accessed directly, and where each element is associated with a geo location.
- A nearest neighbor index (elements in D near <x, y>)
 - Assumption: index returns k elements closest to the point <x,y>

Output

• Estimate

$$\frac{1}{|D|} \sum_{d \in D} f(d)$$



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Output

• Estimate $\frac{1}{|D|} \sum_{d \in D} f(d)$

Applications

- Estimate the size of a population in a region
- Estimate the size of a competing business' database
- Estimate the prevalence of a disease in a region



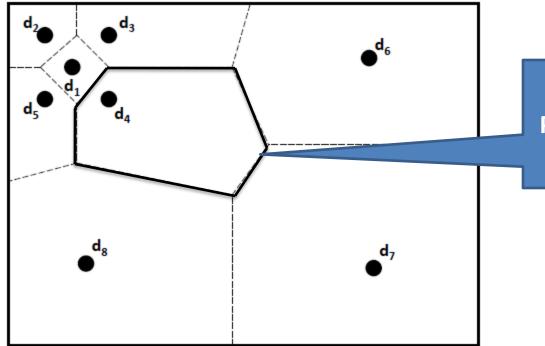
Attempt 1: Naïve geo sampling

For i = 1 to N

- Pick a random point $p_i = \langle x, y \rangle$
- Find element d_i in D that is closes to p_i Return $\hat{f}(D) = \frac{1}{N} \sum_i f(d_i)$



Problem?



Voronoi Cell: Points for which d₄ is the closest element

21

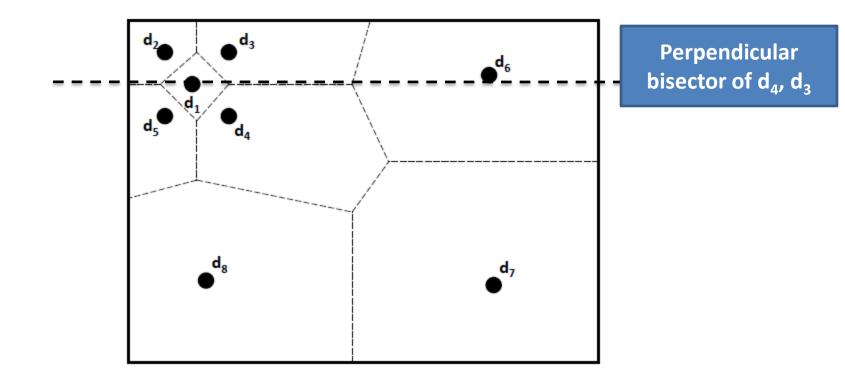
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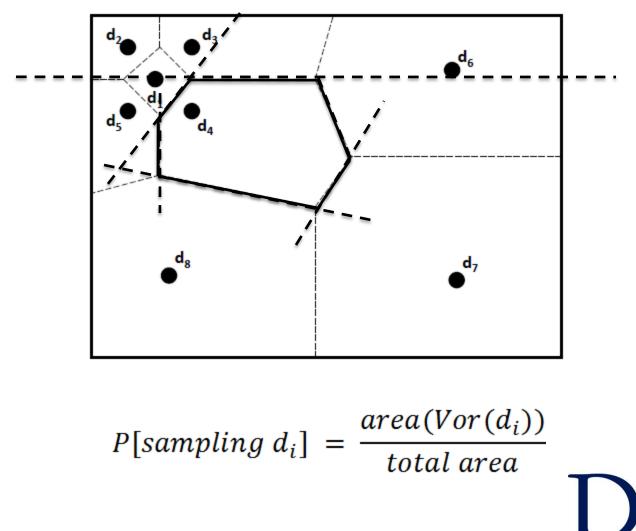
Elements d_7 and d_8 are much more likely to be picked than d_1

Voronoi Decomposition





Voronoi Decomposition



23

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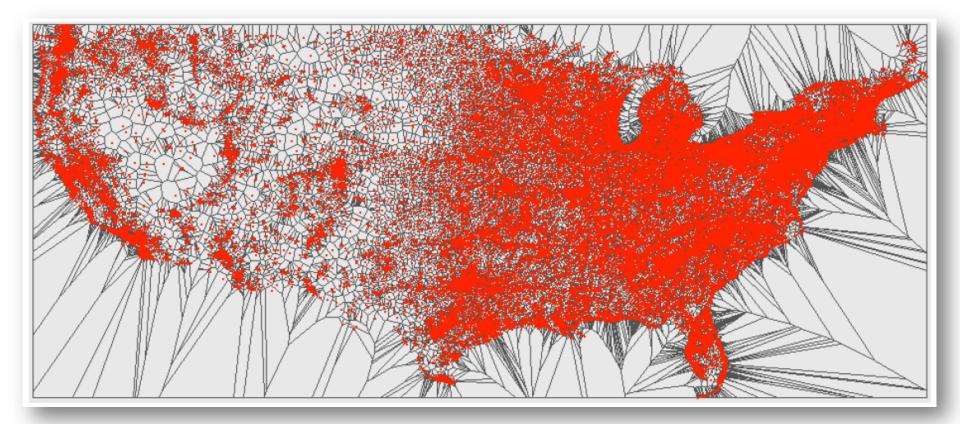
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Voronoi decomposition of Restaurants in US





Attempt 2: Weighted sampling

For i = 1 to N

- Pick a random point p_i = <x,y>
- Find element d_i in D that is closes to p_i

• Return
$$\hat{f}(D) = \frac{1}{N} \sum_{i} \left(f(d_i) \cdot \frac{total area}{area(Vor(d_i))} \right)$$



Attempt 2: Weighted sampling

For i = 1 to N

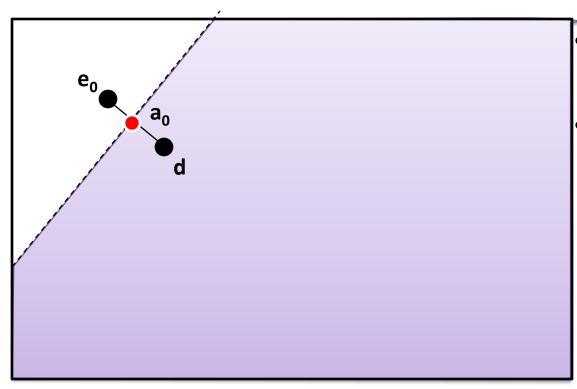
- Pick a random point p_i = <x,y>
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$$\hat{f}(D) = \frac{1}{N} \sum_{i} \left(f(d_i) \cdot \frac{total area}{area(Vor(d_i))} \right)$$

Problem:

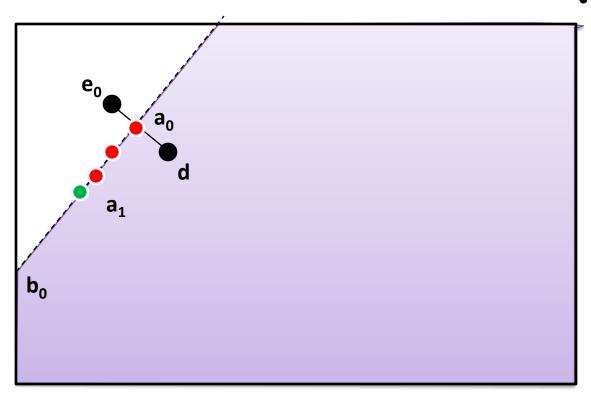
We need to compute the area of the Voronoi cell. We do not have access to other elements in the database.





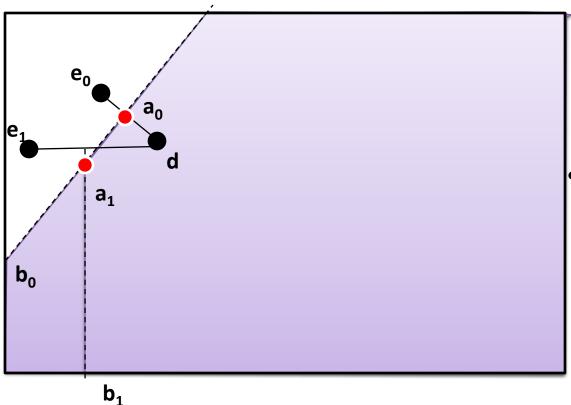
- Find nearest point
- Compute perpendicular bisector
- a0 is a point *on* the Voronoi cell.





- Find a point on (a₀, b₀) which is just inside the Voronoi cell.
 - Use binary search
 - Recursively check whether mid point is in the Voronoi cell



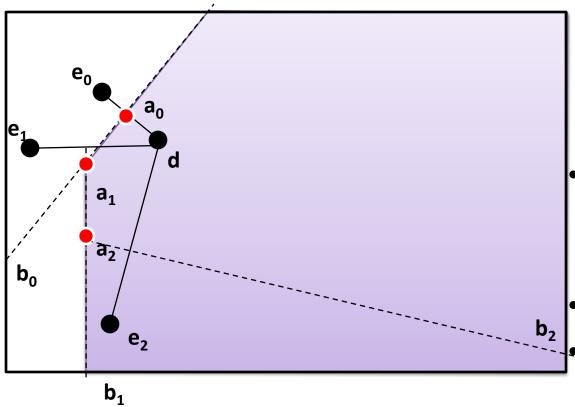


• Find nearest points to

 a_1

- a_1 has to be equidistant to one point other than e_0 and d
- Next direction is perpendicular to (e₁,d)



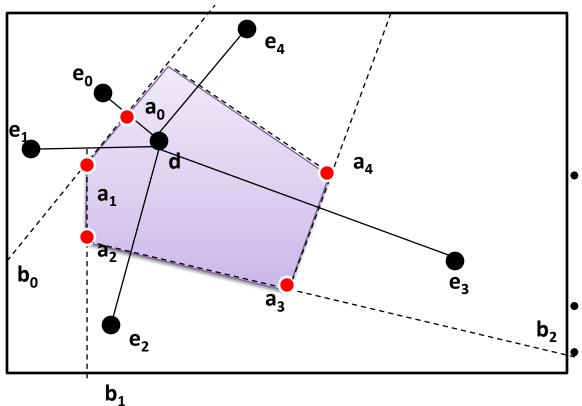


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 - ... and so on ...



Number of samples

- Identifying each a_i requires a binary search
 - If L is the max length of (ai, bi), then a_{i+1} can be computed with ϵ error in O(log (L/ ϵ)) calls to the index
- Identifying the next direction requires another call to the index
- If number of edges of Voronoi cell = k, total number of calls to the index = O(K log(L/ε))
- Average number of edges of a Voronoi cell < 6
 - Assuming general position ...



Summary

- Many web services allow access to databases using nearest neighbor indexes.
- Showed a method to sample uniformly from such databases.
- Next class: Monte Carlo Estimation for #P-hard problems.



References

- F. Olken, "Random Sampling from Databases", PhD Thesis, U C Berkeley, 1993
- N. Dalvi, R. Kumar, A. Machanavajjhala, V. Rastogi, "Sampling Hidden Objects using Nearest Neighbor Oracles", KDD 2011

