## Lecture 23 Classical NP-Hard Problems

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## 1 Hamiltonian Path to TSP Cycle

### 1.1 Problem Analysis

Hamiltonian Path: Given a graph $G$ (directed/undirected), a start vertex $s$ and an end vertex $t$, find a path from $s$ to $t$ that visits every vertex in $G$ exactly once.
Travelling Salesman Problem: Given a weighted graph $G$, and there is a salesman who wants to start at a vertex $s$, visit all vertices and come back to $s$.
Similarity: Visit all vertices
Differences:

1. Hamiltonian Path is on unweighted graphs while TSP is on weighted graphs
2. Path vs. Cycle

### 1.2 Proof

Given a Hamiltonian Path instance with $n$ vertices.To make it a cycle, we can add a vertex $x$, and add edges $(\mathrm{t}, \mathrm{x})$ and $(\mathrm{x}, \mathrm{s})$. To make the path weighted, we can give a weight 1 to all edges. Set $L=n+1$, we now have a TSP cycle instance.
Thus we can conclude that for any Hamiltonian path P in the original graph, the new set of edges $P \cap(t, x),(x, s)$ form a TSP cycle of length $L=n+1$
For any cycle of length $n+1$ that visits every vertex, it must visit every vertex exactly once. Cut the cycle when it visits vertex $x$, (either by $(t, x)$ or $(x, s)$ ). We can thus get a path from $s$ to $t$ that visits every vertex in the original graph exact once.

## 2 3-SAT to quadratic programming

### 2.1 Problem Analysis

### 2.1.1 3-SAT Problem

example: $\left(X_{1} \vee X_{2} \vee \overline{X_{3}}\right) \wedge\left(X_{2} \vee \overline{X_{3}} \vee \overline{X_{4}}\right) \wedge \ldots$
clause: or of 3 literals
literal: $X$ or $\bar{X}$
formula: logical and of many clauses
goal: is there any assignment to the variable such that all clauses are satisfied.

### 2.1.2 Quadratic Programming

variables: $x_{1}, x_{2}, \ldots, x_{n} \in \mathcal{R}$
constraints:

$$
\begin{array}{r}
x_{1}^{2} \leq 3 \\
x_{1}^{2}+2 x_{1} x_{2}-x_{2}^{2} \geq 5 \\
x_{1}^{2}-2 x_{2} \geq x_{3}^{2}-x_{2} x_{3}
\end{array}
$$

goal: Is there an assignment to the variables such that all constraints are satisfied.

### 2.1.3 Comparison

1. boolean variables vs. real variables
2. 3-SAT clauses vs. quadratic constraints

Decision Problem: Given a set of quadratic constraints, does there exist a feasible solution for 3-SAT?

### 2.2 Reduction

In order to create an instance of Quadratic programming from an instance of 3 -SAT, we need to add constraints to make the real variables binary $(0 / 1)$ but adding constraint $y_{i}^{2}=y_{i}$ for all variables $y_{i}$. The negation of the variables in 3 -SAT clauses thus becomes $1-y_{i}$ in quadratic constraints.
Thus, for every clause in 3 -SAT, we thus create a quadratic constraint out of it. For instance, from the clause $x_{a} \vee x_{b} \vee \overline{x_{c}}$ we can create a constraint $y_{a}+y_{b}+\left(1-y_{c}\right) \geq 1$.

## 3 Tripartite matching to subset vector

### 3.1 Problem Analysis

### 3.1.1 Tripartite matching

Given three sets $U, V$ and $W$, each containing $n$ vertices, and hyperedges $(u, v, w)$, where $u \in U, v \in V$ and $w \in W$. A tripartite matching is a way of selecting $n$ hyperedges, so that every vertex is adjacent to a hyperedge. If we want to use $n$ hyperedges to cover all $3 n$ vertices, then we must use exactly one vertex is each of the $n$ edges. Is there is a tripartite matching in the given graph?

### 3.1.2 Subset Vector

Given $n$ vectors $\left\{v_{1}, v_{2}, \ldots, v_{n}\right\}$ and a target vector $u$. The answer is YES iff a subset of these vectors sums up to $u$.

### 3.1.3 Comparison

1. select hyperedges vs. select vectors
2. exact $n$ hyperedges vs. select any number of vectors.

Idea: Encode hyperedges as vectors. For each hyperedges, it includes 3 out of $3 n$ vertices. Thus, we can convert each hyperedge to a one-hot encoding the vertices in the edge. The encoding will be vectors of $3 n$ dimension. For instance, for edge ( $u_{1}, v_{1}, w_{1}$ ), the encoding $E$ will have 0 s in all other indices while $E[0], E[n+1], E[2 n+1]$ will be 1s.
Thus, selecting $n$ hyperedges in order for every vertex in the graph is adjacent to exactly 1 hyper-edge is equivilent to having the sum of these hyper-edge encoded vectors equals to $\overrightarrow{1}$.

## 4 Subset vector to subset sum

### 4.1 Problem Analysis

### 4.1.1 Subset vector

Given $n$ vectors $\left\{v_{1}, v_{2}, \ldots, v_{n}\right\}$ and a target vector $u$. The answer is YES iff a subset of these vectors sums up to $u$.

### 4.1.2 Subset sum

Given $n$ integers $\left\{a_{1}, a_{2}, \ldots, a_{n}\right\}$ and a target $m$. The answer is YES iff a subset of these integers sums up to $m$.

### 4.1.3 Comparison

1. Any integer can be viewed as a vector if we take its base $B$ representation. For instance, integer 9 , if in base 2 , can be seen as a vector $[1,0,0,1]$.
2. Sum of numbers are thus, behave like sum of vectors as long as there is no carry operation.
3. When $B$ is very large, when taking sums, there will be no carry operation.
